

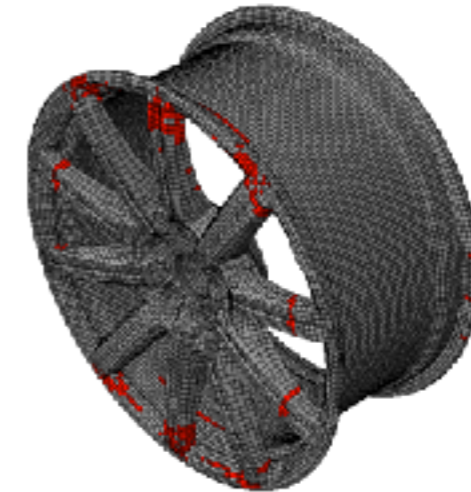
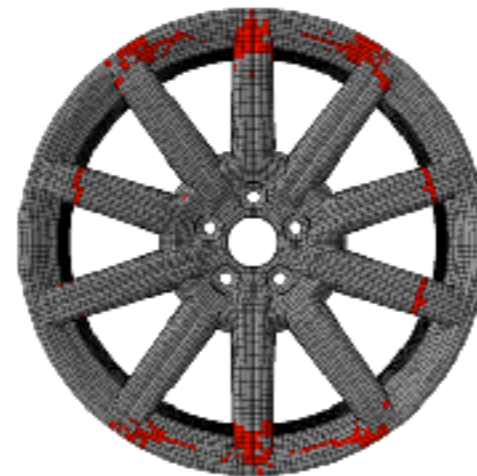
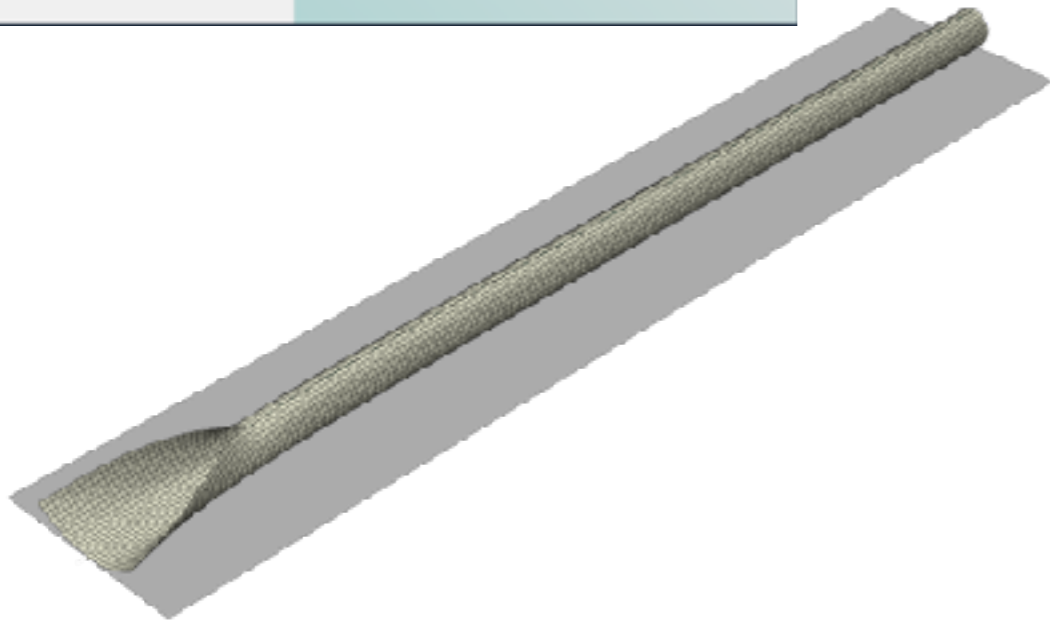
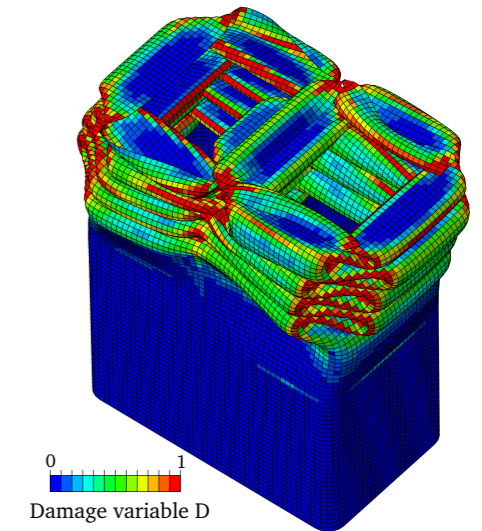
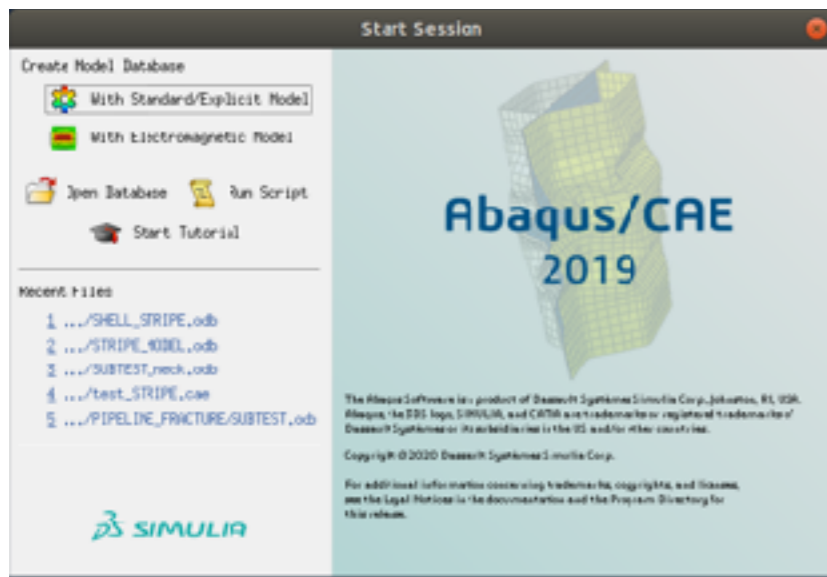
User-defined subroutines for constitutive modelling in ABAQUS

David Morin

Context

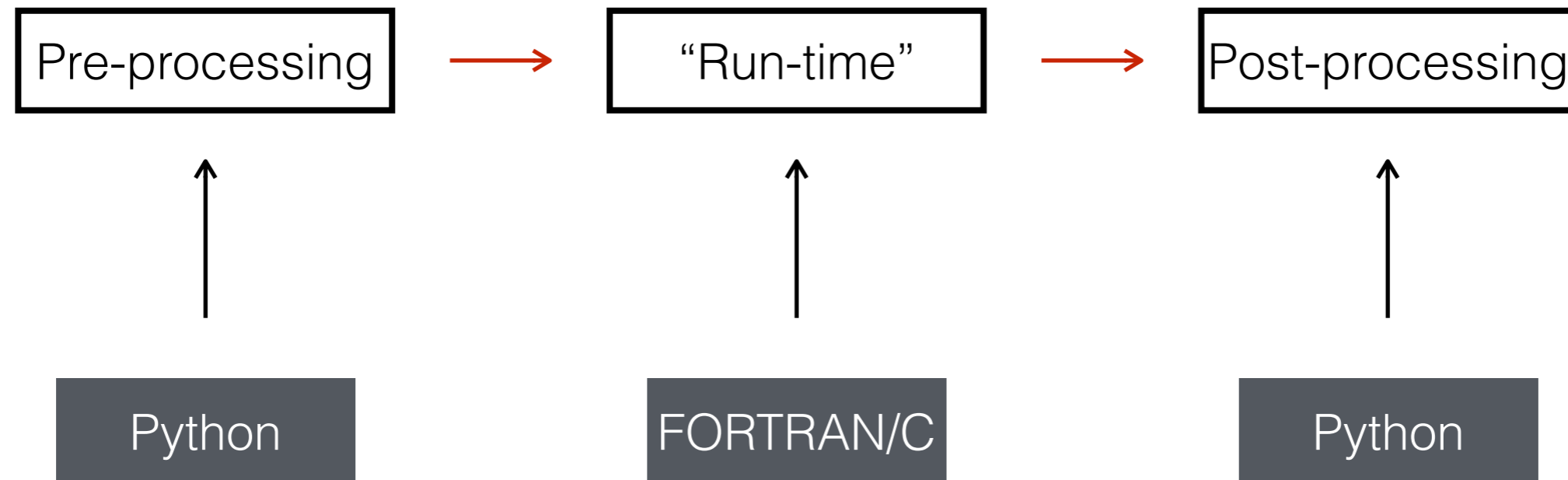
ABAQUS is a powerful Finite Element Analysis (FEA) software...

- Good pre/post-processor
- Many element formulations
- Many material models
- Powerful user coding capabilities



User-coding in ABAQUS

There are 3 “*big*” steps in ABAQUS and all of them offers some kind of user-coding:



User-subroutines in ABAQUS

There are many subroutines available in ABAQUS:

ABAQUS/standard

- GREEP
- DFLOW
- DFLUX
- DIEP
- DLOAD
- FILM
- FLOW
- FRIC
- FRIC_COEF
- GAPCON
- GAPLECTR
- HARDINI
- HETVAL
- MPC
- ORIENT
- RSURFU
- SDVINI
- SGINI
- UAMP
- UANISOHYPER_INV
- UANISOHYPER_STRAIN
- UCORR
- UCREEPNETWORK
- UDAMAGEVF
- UDECURRENT
- UDEMPOENTIAL
- UDMGINI
- UDSECURRENT
- UEL
- UELMAT
- UEACTIVATIONFACET
- UEACTIVATIONSETUP
- UEACTIVATIONVOL
- UEXPAN
- UEXTERNALDB
- UFIELD
- UFLUID
- UFLUIDCONNECTORLOSS
- UFLUIDCONNECTORVALVE
- UFLUIDLEAKOFF
- UFLUIDPIPEFRICTION
- UGENS
- UHARD
- UHYPEL
- UHYPER
- UINTER
- UMASFL
- UMAT
- UMATHT
- UMDFLUX
- UMDFLUXSETUP
- UMESHMOTION
- UMIXMODEFATIGUE
- UMOTION
- UMULLINS
- UPORFP
- UPRESS
- UPSID
- URDFL
- USDFLD
- USUPERELASHARDMOD
- UTEMP
- UTRACLOAD
- UTRS
- UTRSNETWORK
- UYARM
- UWAVE
- UXFEMNONLOCALWEIGHT
- VOIDR

ABAQUS/explicit

- VDFLUX
- VDISP
- VDLOAD
- VEXTERNALDB
- VFABRIC
- VFRIC
- VFRIC_COEF
- VFRICTION
- VHETVAL
- VUAMP
- VUANISOHYPER_INV
- VUANISOHYPER_STRAIN
- VUCHARLENGTH
- VUCREEPNETWORK
- VUEL
- VUEOS
- VUEXPAN
- VUFIELD
- VUFLUIDEXCH
- VUFLUIDEXCHEFFAREA
- VUHARD
- VUINTER
- VUINTERACTION
- VUMAT
- VUMATHT
- VUMULLINS
- VUSDFLD
- VUSUPERELASHARDMOD
- VUTRS
- VUVISCOSITY
- VWAVE

User-subroutines in ABAQUS

ABAQUS/standard and ABAQUS/explicit do not have the same subroutines:

- ABAQUS/explicit uses a vectorised system
- ABAQUS/standard uses a scalar system

ABAQUS/standard

One integration point

subroutine()



end subroutine

ABAQUS/explicit

A block of integration point

subroutine()

do i=1,nblock



enddo

end subroutine

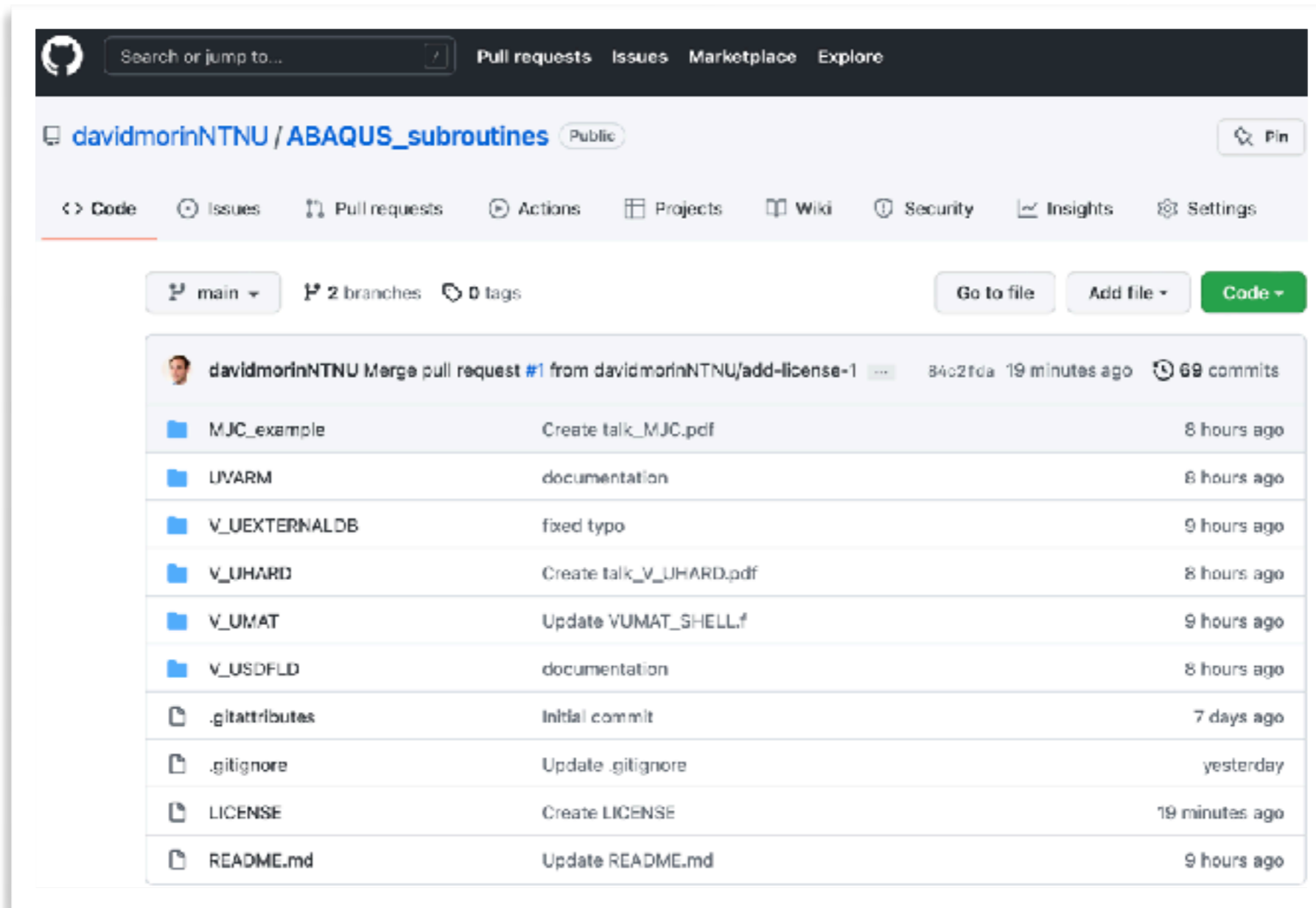


This lecture covers only some subroutines related to “material modelling”

User-subroutines in ABAQUS

To get started:

https://github.com/davidmorinNTNU/ABAQUS_subroutines



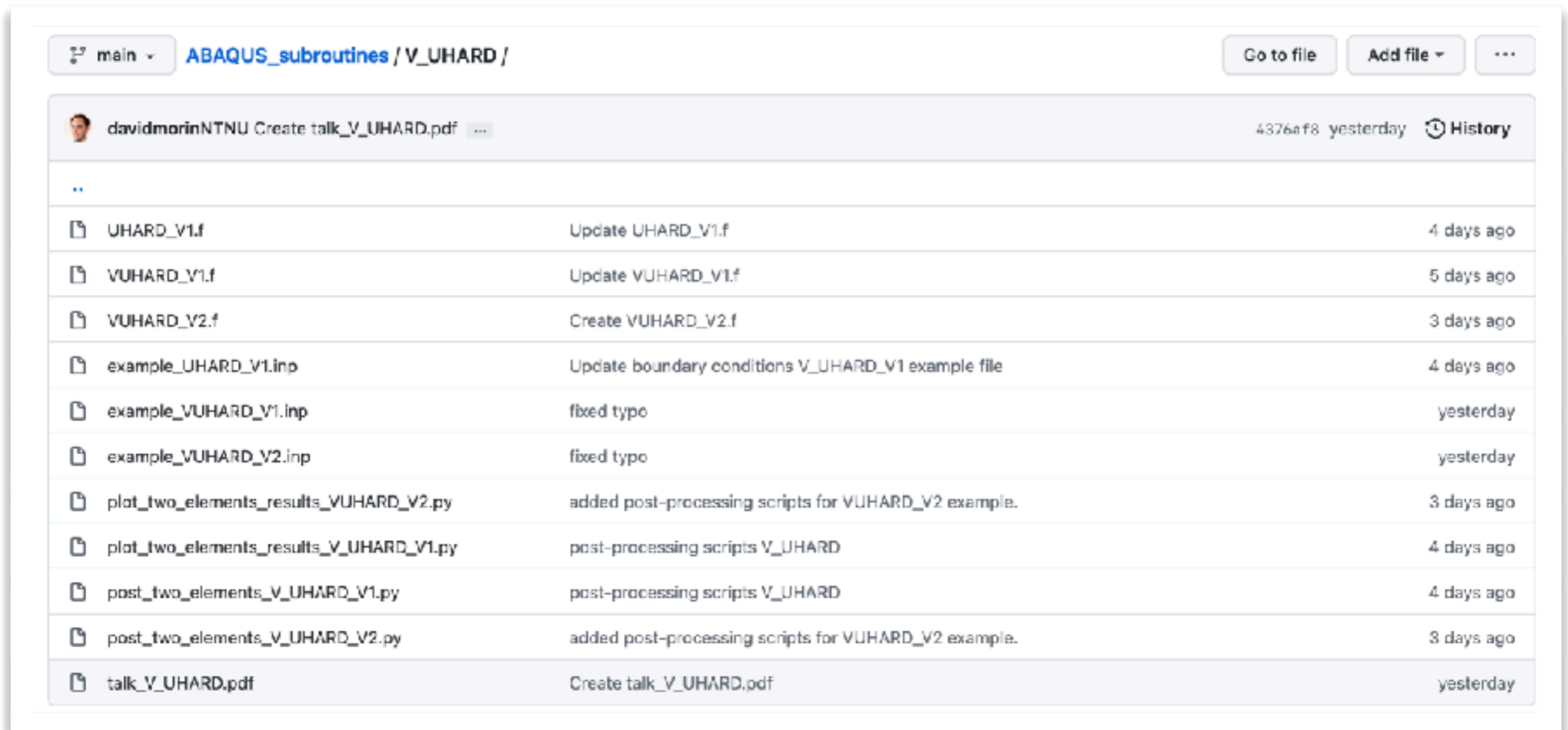
The screenshot displays the GitHub interface for the repository `davidmorinNTNU / ABAQUS_subroutines`. The repository is public and has 2 branches and 0 tags. The main branch is selected. The repository contains several folders and files, with the following recent commits:

Commit	Message	Time	
84c2fda	Merge pull request #1 from davidmorinNTNU/add-license-1	19 minutes ago	
	69 commits		
	MJC_example	Create talk_MJC.pdf	8 hours ago
	UVARM	documentation	8 hours ago
	V_UEXTERNALDB	fixed typo	9 hours ago
	V_UHARD	Create talk_V_UHARD.pdf	8 hours ago
	V_UMAT	Update VUMAT_SHELL.f	9 hours ago
	V_USDFLD	documentation	8 hours ago
	.gitattributes	Initial commit	7 days ago
	.gitignore	Update .gitignore	yesterday
	LICENSE	Create LICENSE	19 minutes ago
	README.md	Update README.md	9 hours ago

User-subroutines in ABAQUS

To get started:

https://github.com/davidmorinNTNU/ABAQUS_subroutines



The screenshot shows the GitHub interface for the repository `ABAQUS_subroutines / V_UHARD /`. The current branch is `main`. The repository was last updated by `davidmorinNTNU` with commit `4376af8` yesterday. The file list includes:

File Name	Commit Message	Time Ago
..		
UHARD_V1.f	Update UHARD_V1.f	4 days ago
VUHARD_V1.f	Update VUHARD_V1.f	5 days ago
VUHARD_V2.f	Create VUHARD_V2.f	3 days ago
example_UHARD_V1.inp	Update boundary conditions V_UHARD_V1 example file	4 days ago
example_VUHARD_V1.inp	fixed typo	yesterday
example_VUHARD_V2.inp	fixed typo	yesterday
plot_two_elements_results_VUHARD_V2.py	added post-processing scripts for VUHARD_V2 example.	3 days ago
plot_two_elements_results_V_UHARD_V1.py	post-processing scripts V_UHARD	4 days ago
post_two_elements_V_UHARD_V1.py	post-processing scripts V_UHARD	4 days ago
post_two_elements_V_UHARD_V2.py	added post-processing scripts for VUHARD_V2 example.	3 days ago
talk_V_UHARD.pdf	Create talk_V_UHARD.pdf	yesterday

User-subroutines in ABAQUS

Why should we develop/implement something into ABAQUS?

- Lack of a particular model
- Improvement of an existing model

Things to consider before implementing any model:



- Can you work with an existing model?
- Will someone else use your code?

User-subroutines in ABAQUS

UEL/VUEL

UEL: User subroutine to define an element.

UMAT/VUMAT

UMAT: User subroutine to define a material's mechanical behavior.

V-UEXTERNALDB

UEXTERNALDB: User subroutine to manage user-defined external databases and calculate model-independent history information.

UHARD/VUHARD

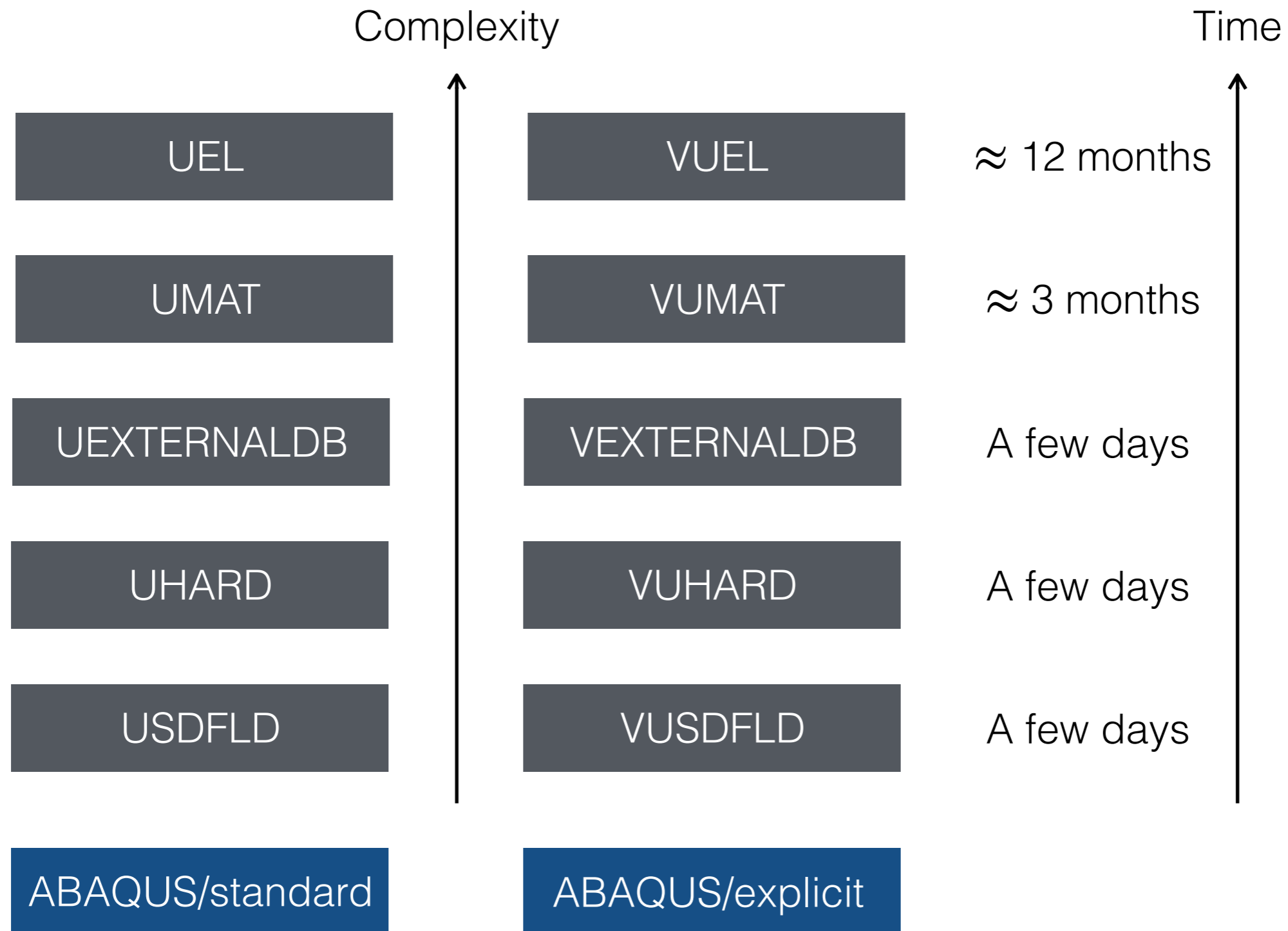
UHARD: User subroutine to define the yield surface size and hardening parameters for isotropic plasticity or combined hardening models.

USDFLD/VUSDFLD

USDFLD: User subroutine to redefine field variables at a material point.

ABAQUS

User-subroutines in ABAQUS



(V)USDFLD subroutine

USDFLD: User subroutine to redefine field variables at a material point.

VUSDFLD: User subroutine to redefine field variables at a material point.

(V)USDFLD subroutine

ABAQUS/standard

Overview

User subroutine **USDFLD**:

- allows you to define field variables at a material point as functions of time or of any of the available material point quantities listed in the Output Variable Identifiers table (“Abaqus/Standard output variable identifiers,” Section 4.2.1 of the Abaqus Analysis User’s Guide) except the user-defined output variables **UARM** and **UARM_n**;
- can be used to introduce solution-dependent material properties since such properties can easily be defined as functions of field variables;
- will be called at all material points of elements for which the material definition includes user-defined field variables;
- must call utility routine **GETVRM** to access material point data;
- can use and update state variables; and
- can be used in conjunction with user subroutine **UFIELD** to prescribe predefined field variables.

State dependent variables

Field variables

ABAQUS/explicit

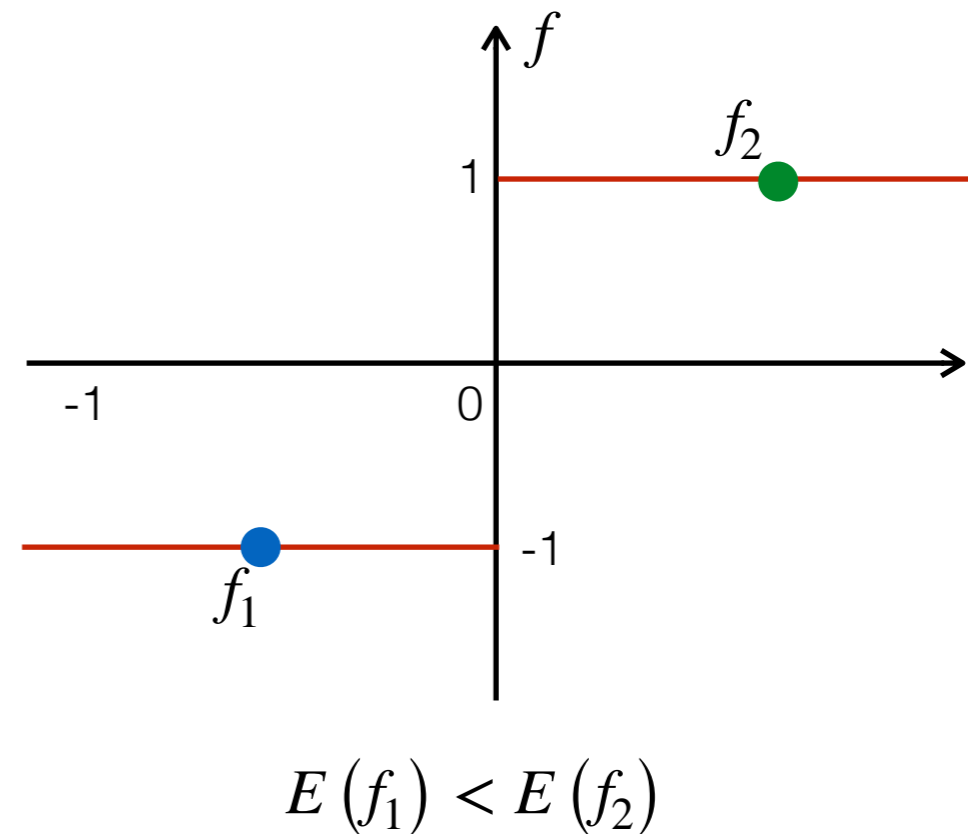
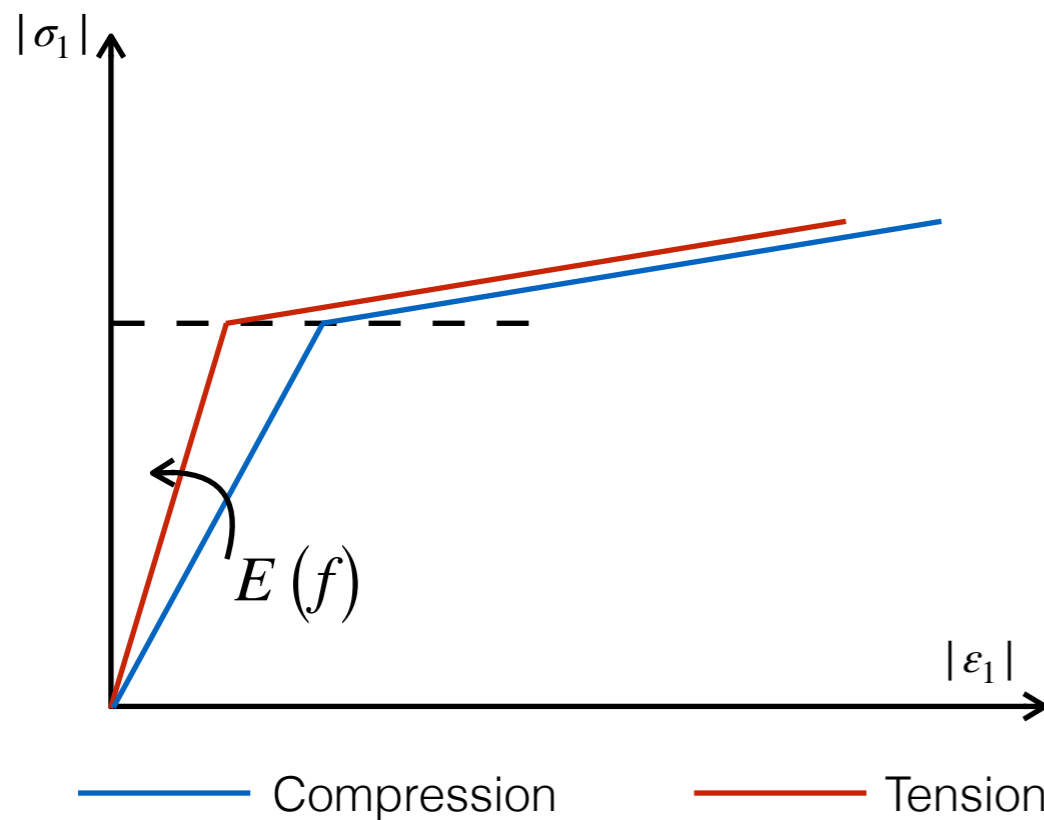
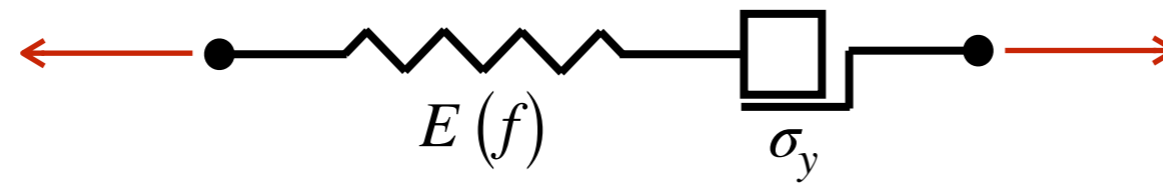
Overview

User subroutine **VUSDFLD**:

- allows the redefinition of field variables at a material point as functions of time or of any of the available material point quantities listed in “Available output variable keys” in “Obtaining material point information in an Abaqus/Explicit analysis,” Section 2.1.7;
- can be used to introduce solution-dependent material properties since such properties can be easily defined as functions of field variables;
- will be called at all material points of elements for which the material definition includes user-defined field variables;
- can call utility routine **VGETVRM** to access material point data; and
- can use and update solution-dependent state variables.

(V)USDFLD subroutine

In this example, we want a material model where the Young's modulus E is different between tension and compression.



(V)USDFLD subroutine

Material cards for both solvers are identical.

ABAQUS/explicit

```
77  **-----
78  ** MATERIALS
79  **-----
80  *material,name=EXAMPLE_VUSDFD_V1
81  *density
82  7.8e-9
83  *elastic,dependencies=1
84  **      E,  NU,  TEMP,  F
85  | 21000.0, 0.3,  0.0, -1.0
86  | 210000.0, 0.3,  0.0,  1.0
87  *plastic
88  250.0, 0.0
89  350.0, 1.0
90  *User defined field
91  **-----
```

Activate a field dependency

Tabulated data with the field variable f
Temperature must always be present

Call to the VUSDFLD subroutine

ABAQUS/standard

```
77  **-----
78  ** MATERIALS
79  **-----
80  *material,name=EXAMPLE_USDFD_V1
81  *elastic,dependencies=1
82  **      E,  NU,  TEMP,  F
83  | 21000.0, 0.3,  0.0, -1.0
84  | 210000.0, 0.3,  0.0,  1.0
85  *plastic
86  250.0, 0.0
87  350.0, 1.0
88  *User defined field
89  **-----
```

(V)USDFLD subroutine

```
6 SUBROUTINE USDFLD(FIELD, STATEV, PNEWDT, DIRECT, T, CELENT,  
7 + TIME, DTIME, CMNAME, ORNAME, NFIELD, NSTATV, NOEL, NPT, LAYER,  
8 + KSPT, KSTEP, KINC, NDI, NSHR, COORD, JMAC, JMATYP, MATLAYO, LACCFLA)  
9 INCLUDE 'ABA_PARAM.INC'  
10  
11 !-----Declaration ABAQUS variables  
12 !-----  
13 CHARACTER*30 CMNAME, ORNAME  
14 DIMENSION FIELD(NFIELD), STATEV(NSTATV), DIRECT(3,3)  
15 DIMENSION T(3,3), TIME(2), COORD(*), JMAC(*), JMATYP(*)  
16 !-----Data from ABAQUS  
17 DIMENSION ARRAY(15), JARRAY(15)  
18 CHARACTER*3 FLGRAY(15)  
19  
20 !-----Declaration internal variables  
21 !-----  
22 real*8 SIGH, SMISES, TRIAX  
23  
24 ! Access stress invariants  
25 !-----  
26 CALL GETVRM('STNV', ARRAY, JARRAY, FLGRAY, JRCO,  
27 + JMAC, JMATYP, MATLAYO, LACCFLA)  
28  
29 SIGH = ARRAY(3)  
30 SMISES = ARRAY(1)
```

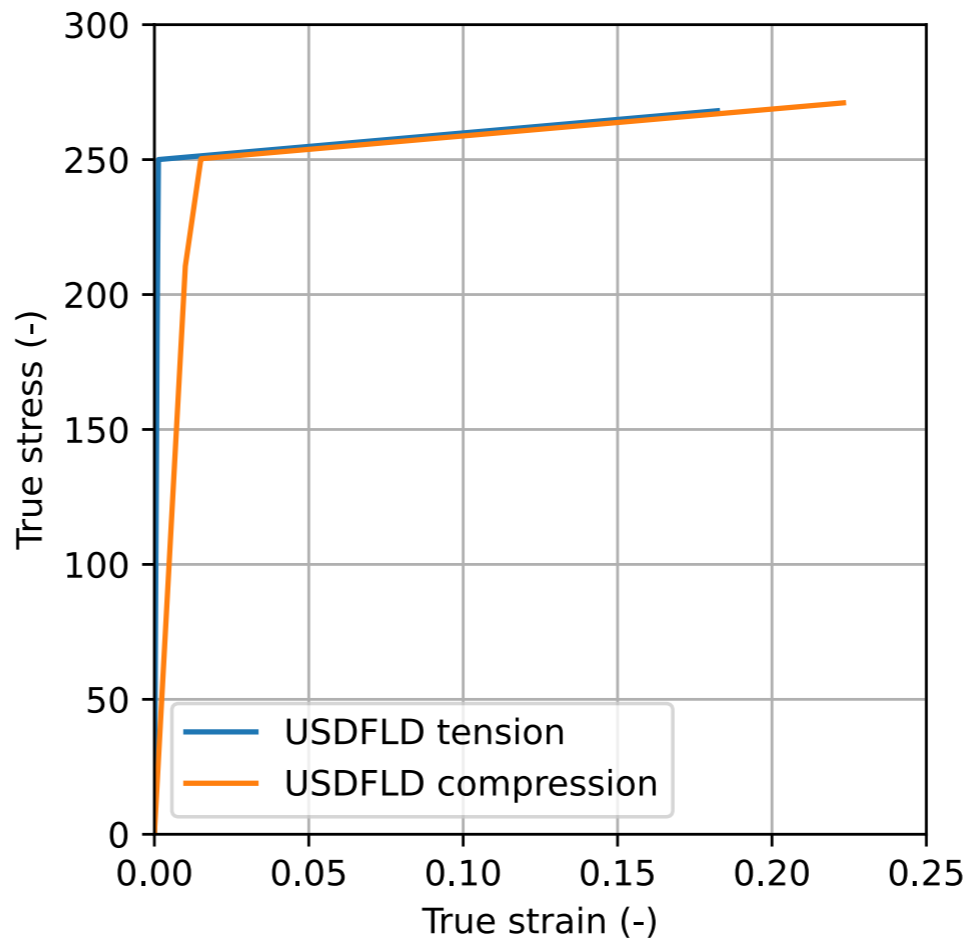
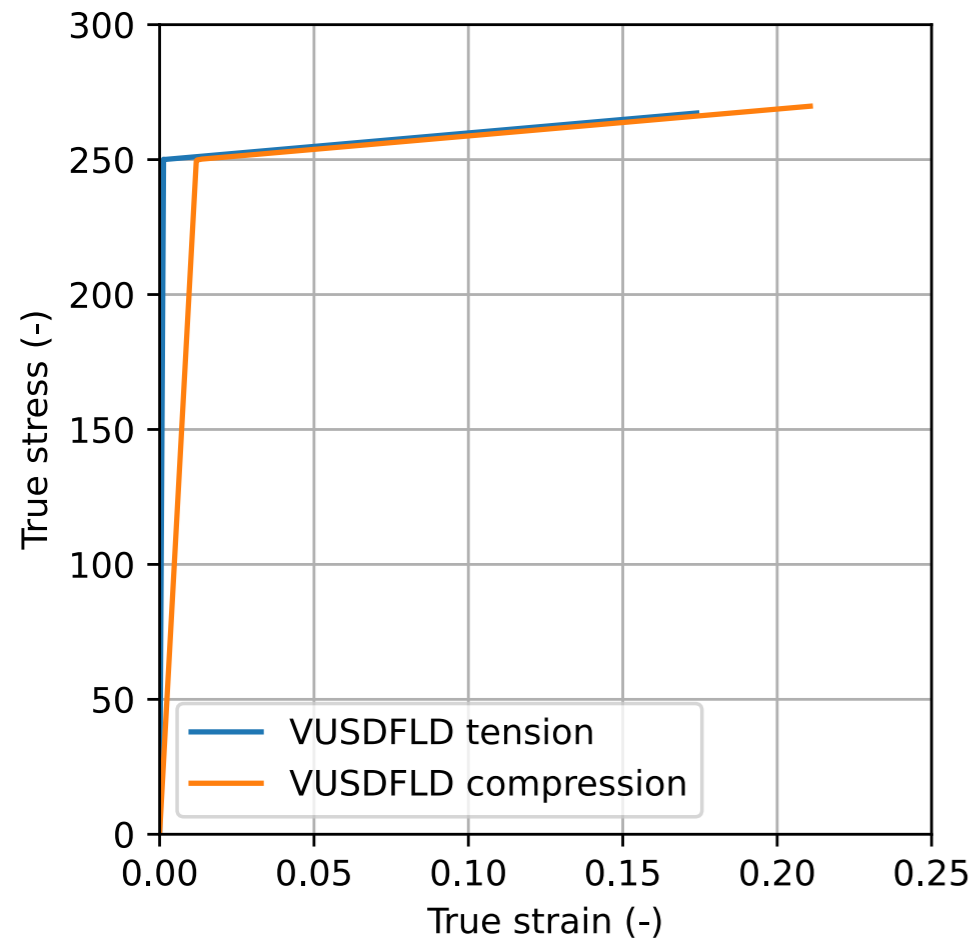
Access to ABAQUS variables

```
31 !-----  
32 ! Compute the stress triaxiality  
33 !-----  
34 if(SMISES.gt.0.0)then  
35 | TRIAX = -SIGH/SMISES  
36 else  
37 | TRIAX = 0.0  
38 endif  
39 !-----  
40 ! Update field variable  
41 !-----  
42 if(TRIAX.ge.0.0)then  
43 | FIELD(1) = 1.05  
44 else  
45 | FIELD(1) = -1.05  
46 endif  
47 !-----  
48 ! End of subroutine  
49 !-----  
50 RETURN  
51 END
```

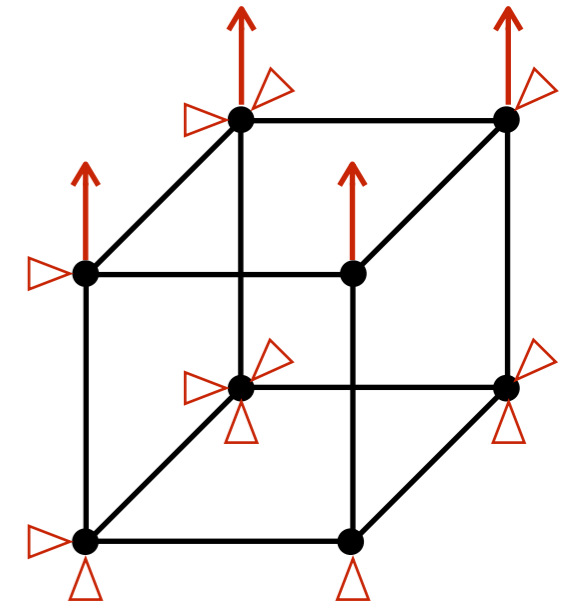
Field variable f

(V)USDFLD subroutine

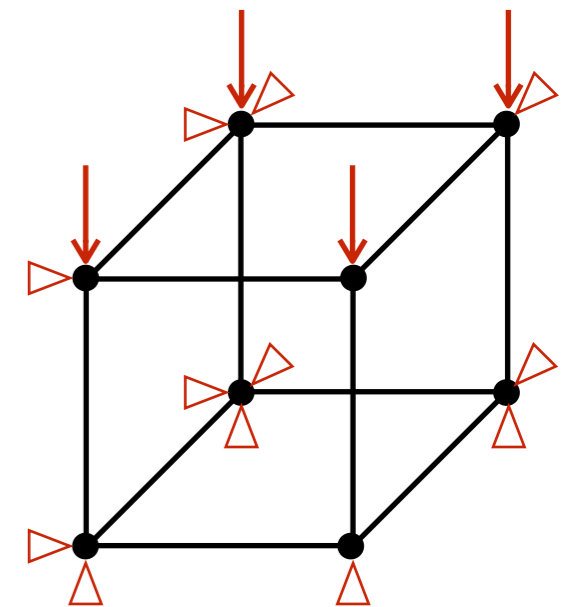
Results from the USDFLD_V1 and VUSDFLD_V1 subroutines



Single solid element in uniaxial tension



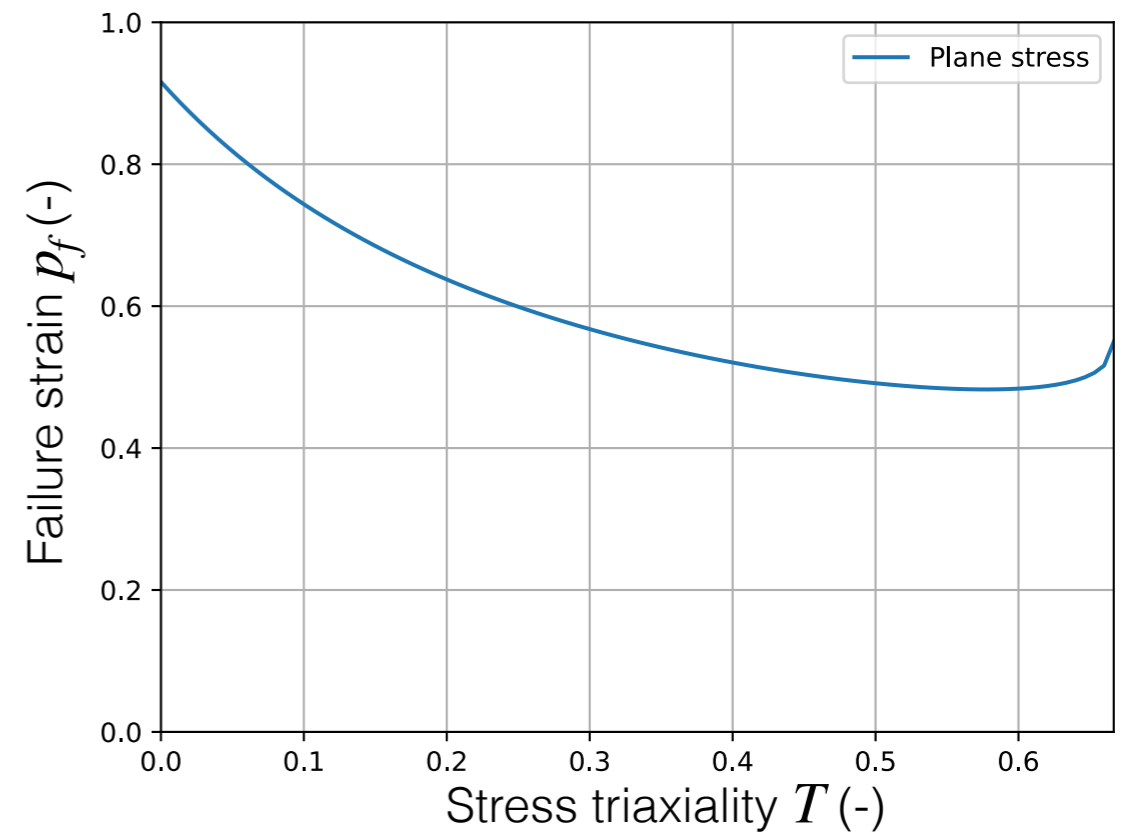
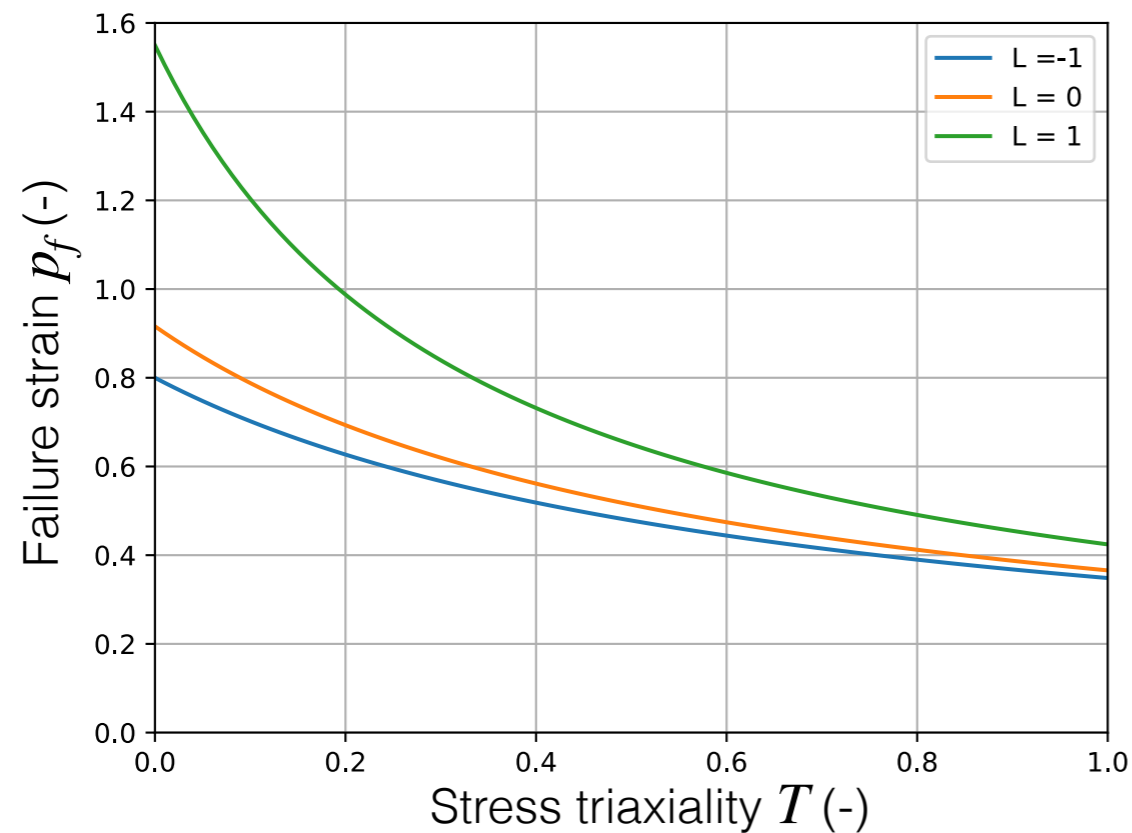
Single solid element in uniaxial compression



(V)USDFLD subroutine

In this example, we want to add a user-defined fracture model to a built-in plasticity model from ABAQUS.

Cockcroft-Latham criterion:
$$D = \int_0^{p_f} \frac{\langle \sigma_1 \rangle}{W_c} dp \leq 1$$



(V)USDFLD subroutine

Cockcroft-Latham criterion:

$$D = \int_0^{P_f} \frac{\langle \sigma_1 \rangle}{W_c} dp \leq 1$$

Call to the VUSDFLD subroutine

W_c

State dependent variables

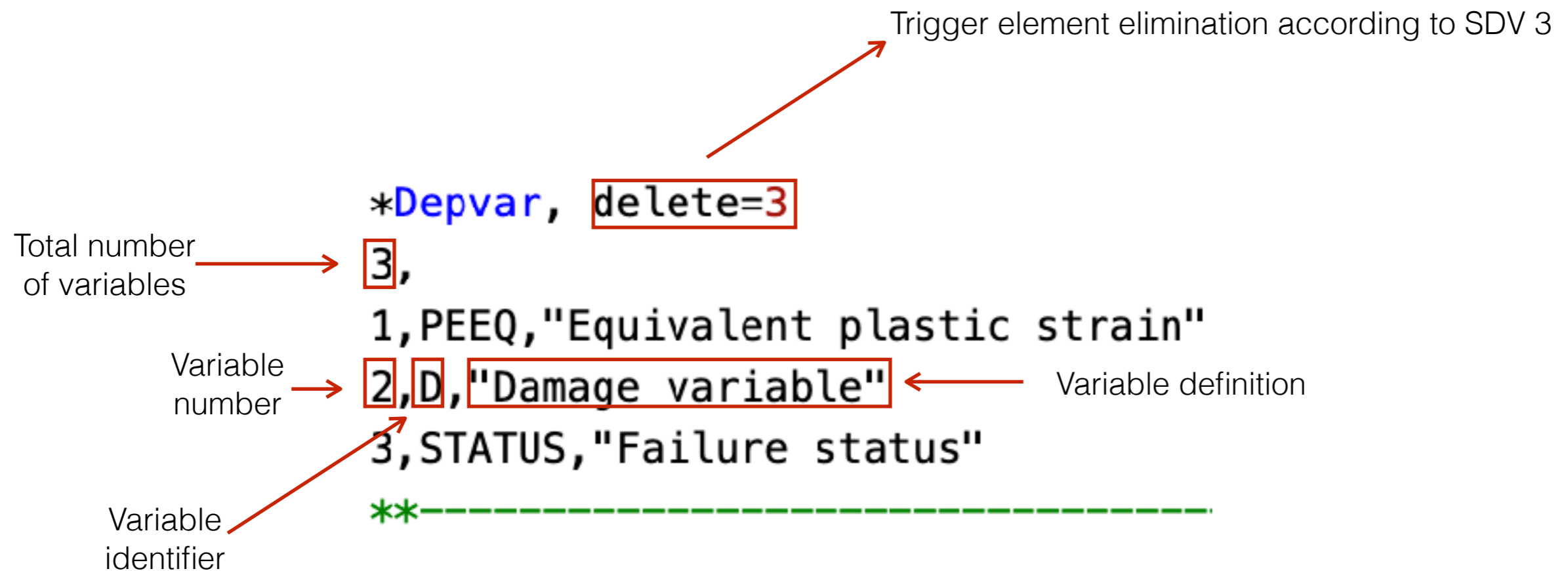
```
**-----  
** MATERIALS  
**-----  
*material, name=EXAMPLE_VUSDFLD_V2  
*density  
7.8e-9  
*elastic  
210000.0, 0.3  
*plastic  
250.0, 0.0  
350.0, 1.0  
*User defined field, properties=1  
100.0  
*Depvar, delete=3  
3,  
1,PEEQ,'Equivalent plastic strain'  
2,D,'Damage variable'  
3,STATUS,'Failure status'  
**-----
```



Properties can not be given to the ABAQUS/standard USDFLD subroutine

(V)USDFLD subroutine

State Dependent Variables (SDV):



(V)USDFLD subroutine

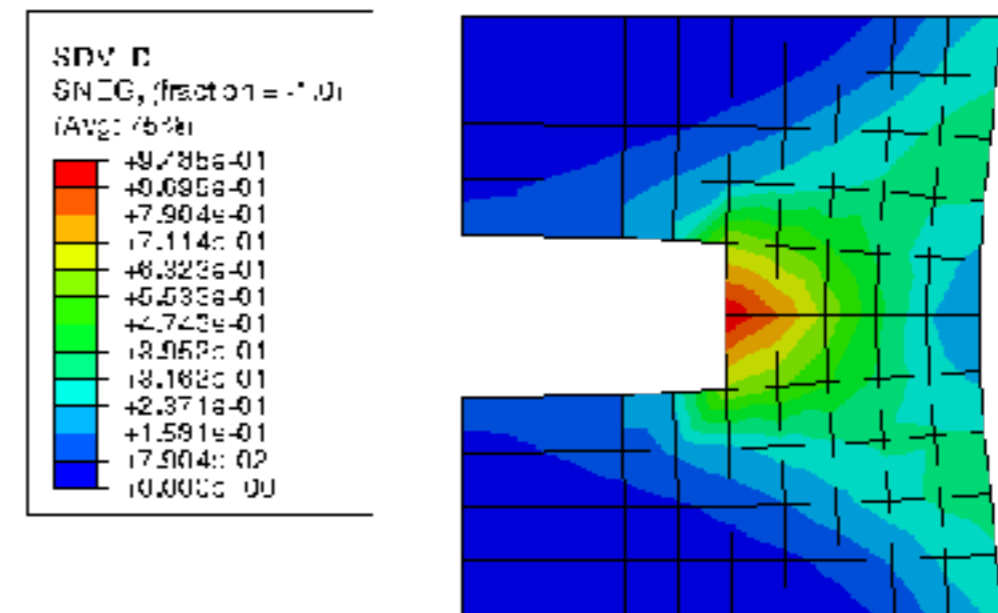
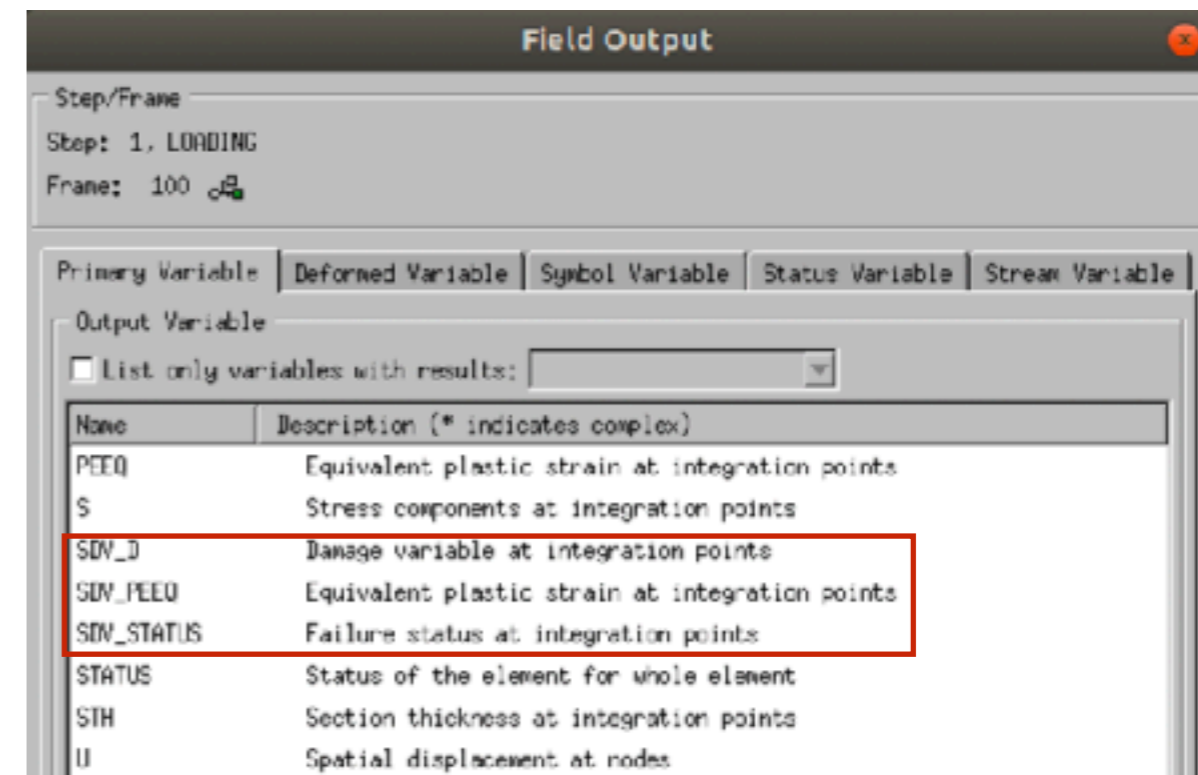
Input file structure:

```
**-----  
** FIELD OUTPUT  
**-----  
*Output, field, number interval=100, time marks=YES  
*Element Output, directions=YES  
PEEQ, S, SDV, STATUS  
*Node Output  
U
```

State dependent variables

Status for element elimination (from odb file)

Odb file structure:



(V)USDFLD subroutine

ABAQUS/standard

ABAQUS/explicit

Status = 0 means inactive (failed) integration point

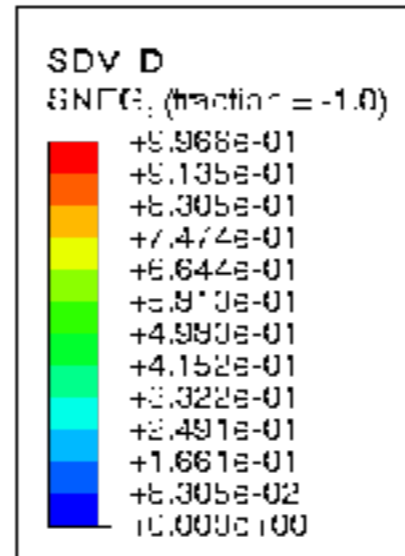
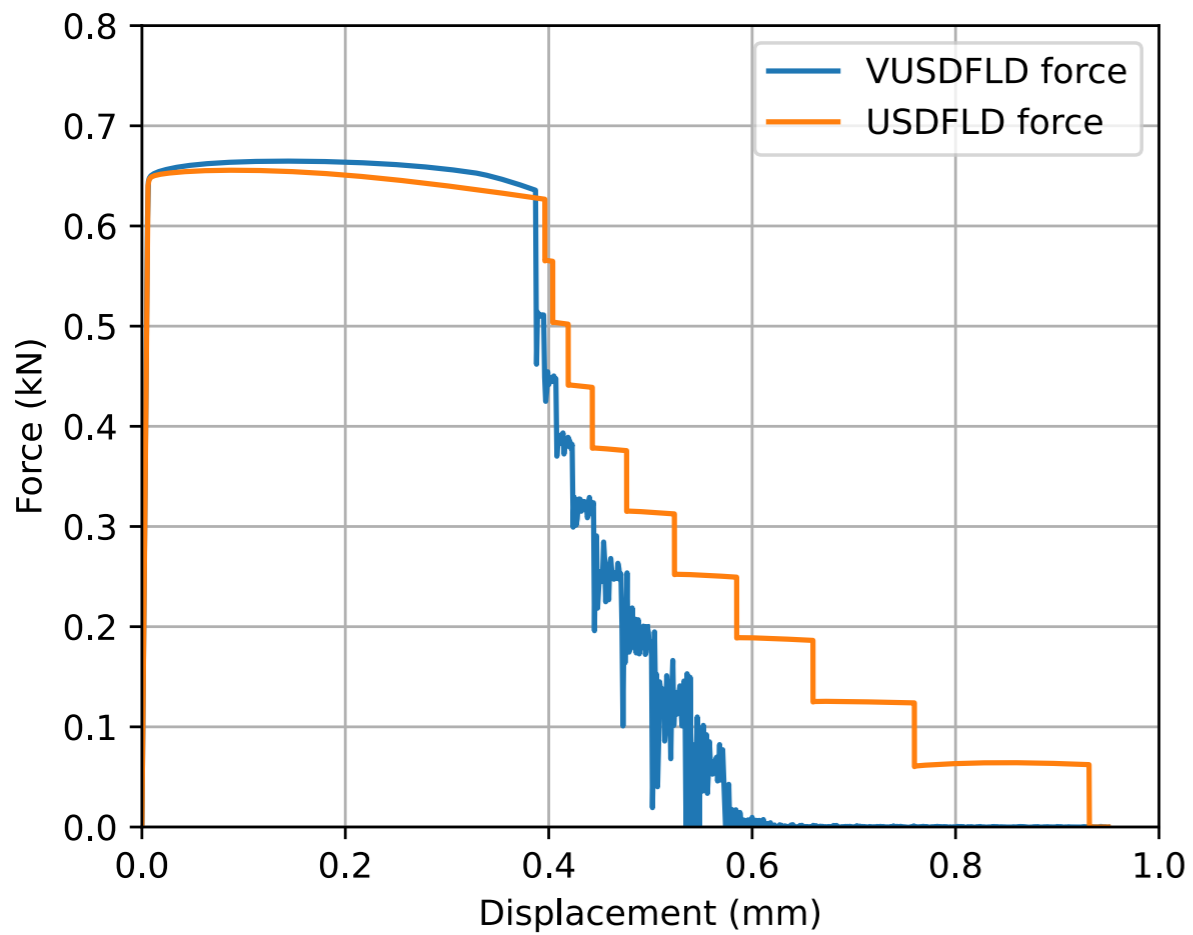
```
63 !-----  
64 !   Check for fracture  
65 !-----  
66   if(damage.ge.1.0)then  
67     STATEV(3) = 0.0  
68   else  
69     STATEV(3) = 1.0  
70   endif  
71 !-----
```

```
101 !-----  
102 !   Check for fracture  
103 !-----  
104   do i=1,nblock  
105     if(damage(i).ge.1.0)then  
106       stateNew(i,3) = 0.0  
107     else  
108       stateNew(i,3) = 1.0  
109     endif  
110   enddo
```

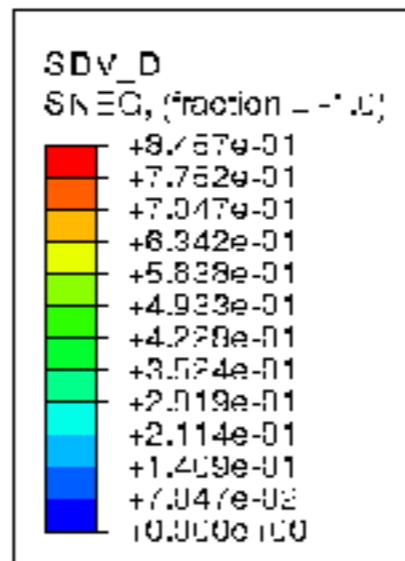
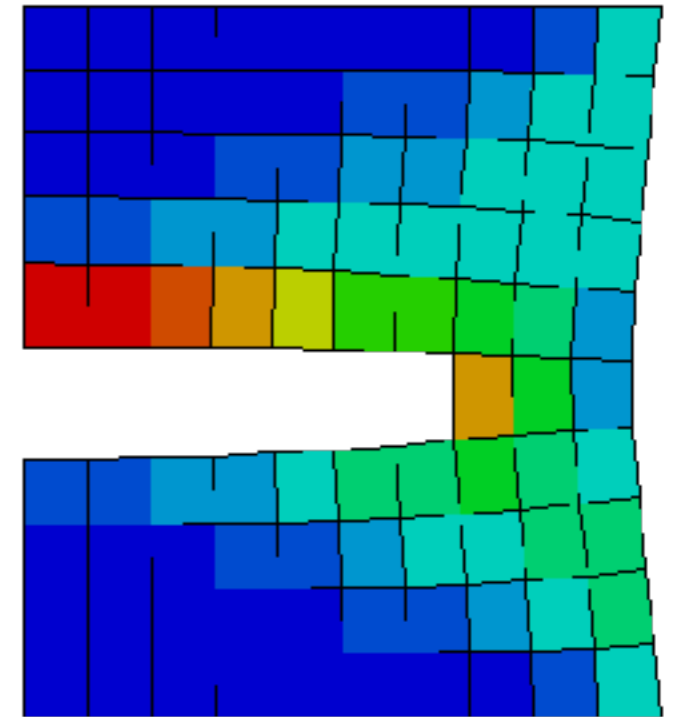
Status = 1 means active integration point

(V)USDFLD subroutine

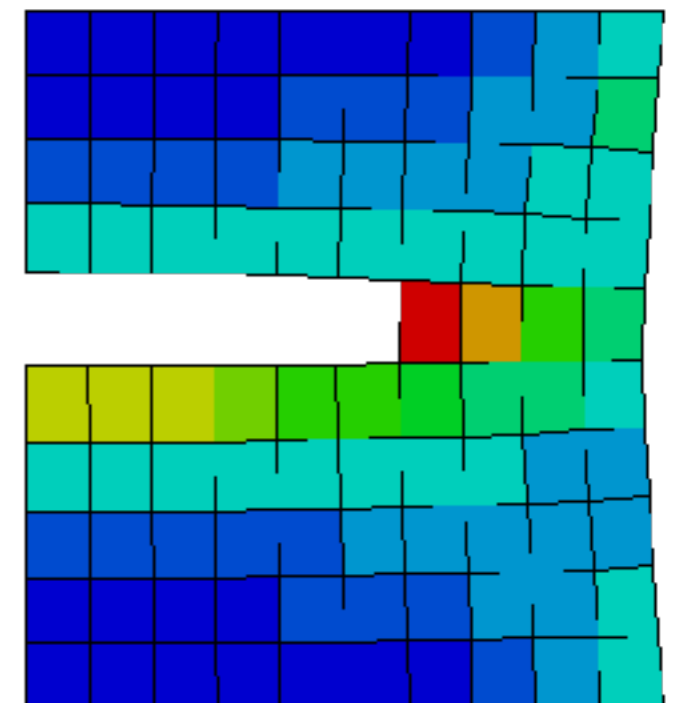
Results from the USDFLD_V2 and VUSDFLD_V2 subroutines



VUSDFLD_V2



USDFLD_V2



(V)USDFLD subroutine

These are quite flexible subroutine which can be used for various applications.



- No properties for the USDFLD subroutine (only for explicit)
- The explicit update of SDVs
- Limited number of variables in ABAQUS/explicit accessible through the vgetvrm subroutine.

(V)UMAT subroutine

UMAT: User subroutine to define a material's mechanical behavior.



WARNING: The use of this subroutine generally requires considerable expertise. You are cautioned that the implementation of any realistic constitutive model requires extensive development and testing. Initial testing on a single-element model with prescribed traction loading is strongly recommended.

VUMAT: User subroutine to define material behavior.

(V)UMAT subroutine

Overall principle:

Hypo-elastic(-plastic) material model: $\boldsymbol{\varepsilon} = \boldsymbol{\varepsilon}_e + \boldsymbol{\varepsilon}_p$



Hyper-elastic(-plastic) material model: $\mathbf{F} = \mathbf{F}_e \cdot \mathbf{F}_p$

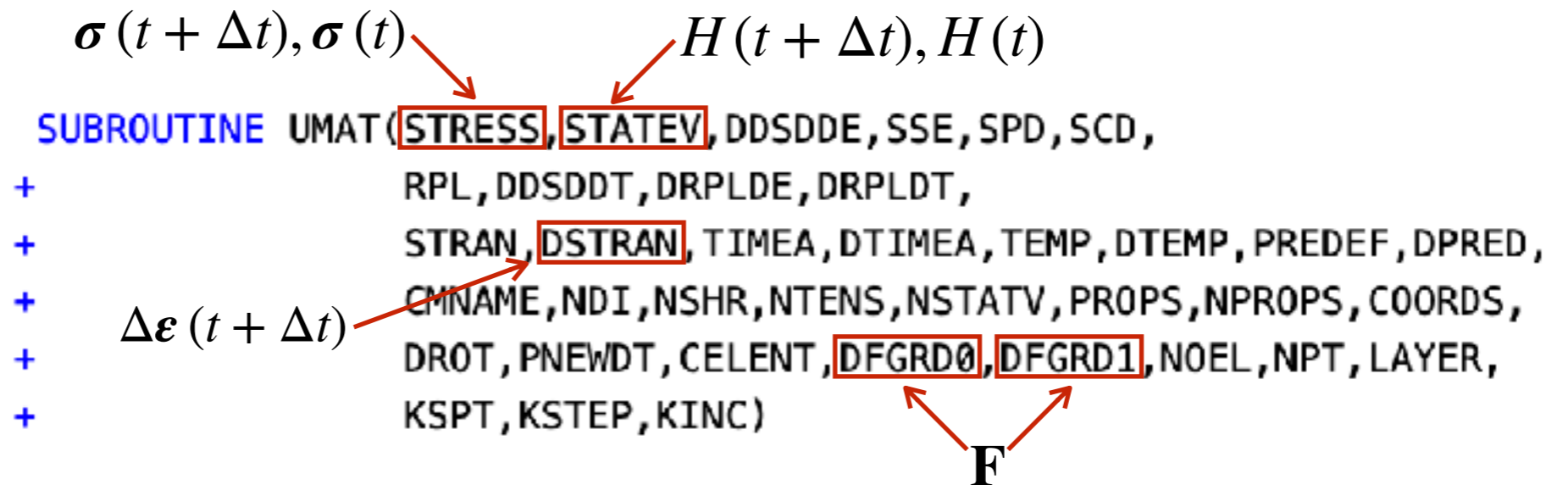


H are the State Dependent Variables

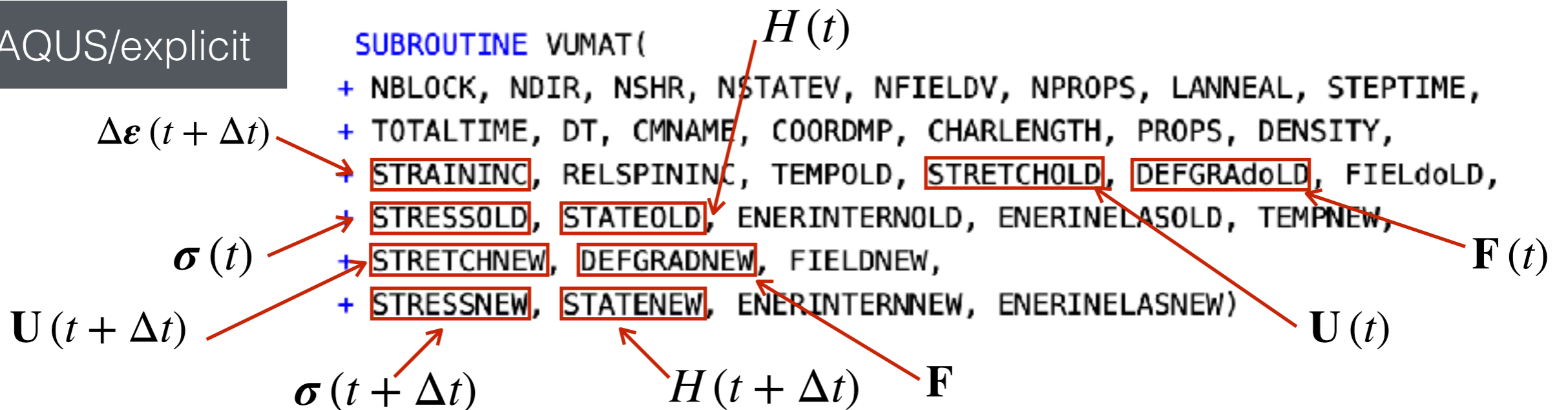
Deformation gradient tensor \mathbf{F}

(V)UMAT subroutine

ABAQUS/standard



ABAQUS/explicit



(V)UMAT subroutine



Some differences between UMAT and VUMAT

ABAQUS/standard

ABAQUS/explicit

$$\boldsymbol{\sigma} = \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{12} \\ \sigma_{31} \\ \sigma_{23} \end{bmatrix} \quad \boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \\ 2\varepsilon_{12} \\ 2\varepsilon_{31} \\ 2\varepsilon_{23} \end{bmatrix}$$

Ordering tensor components

$$\boldsymbol{\sigma} = \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{12} \\ \sigma_{23} \\ \sigma_{31} \end{bmatrix} \quad \boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \\ \varepsilon_{12} \\ \varepsilon_{23} \\ \varepsilon_{31} \end{bmatrix}$$

Jaumann:

$$\boldsymbol{\sigma}^{\nabla J} = \dot{\boldsymbol{\sigma}} - \mathbf{W} \cdot \boldsymbol{\sigma} + \boldsymbol{\sigma} \cdot \mathbf{W}$$

Stress rate
(objectivity)

Green-Naghdi:

$$\boldsymbol{\sigma}^{\nabla G} = \dot{\boldsymbol{\sigma}} - \boldsymbol{\Omega} \cdot \boldsymbol{\sigma} + \boldsymbol{\sigma} \cdot \boldsymbol{\Omega}$$



The user must ensure the objectivity of all tensor stored in the state dependent variables

The objectivity of all tensor stored in the state dependent variables is handled by ABAQUS

(V)UMAT subroutine

The implicit solver requires the tangent operator $\frac{\partial \Delta \sigma}{\partial \Delta \epsilon}$ to form the stiffness matrix of the model.

ABAQUS/standard

```
SUBROUTINE UMAT(STRESS, STATEV, DDSDDDE, SSE, SPD, SCD,  
+ RPL, DDSDDT, DRPLDE, DRPLDT,  
+ STRAN, DSTRAN, TIMEA, DTIMEA, TEMP, DTEMP, PREDEF, DPRED,  
+ CMNAME, NDI, NSHR, NTENS, NSTATV, PROPS, NPROPS, COORDS,  
+ DROT, PNEWDT, CELENT, DFGRD0, DFGRD1, NOEL, NPT, LAYER,  
+ KSPT, KSTEP, KINC)
```

- The tangent operator (DDSDDDE) is a common source of error leading to slow convergence and crashes
- By default the consistent tangent operator is expected (full newton solver)
- A workaround:
 - Supply the elasticity matrix into DDSDDDE
 - Use the quasi-newton solution technique

(V)UMAT subroutine

ABAQUS/explicit

At the first time step:

- A purely elastic computation for time-step computation
- Be careful with visco-elasticity, anisotropic elasticity...

$$\Delta t \approx l_e \sqrt{\frac{\rho}{E}}$$

where:

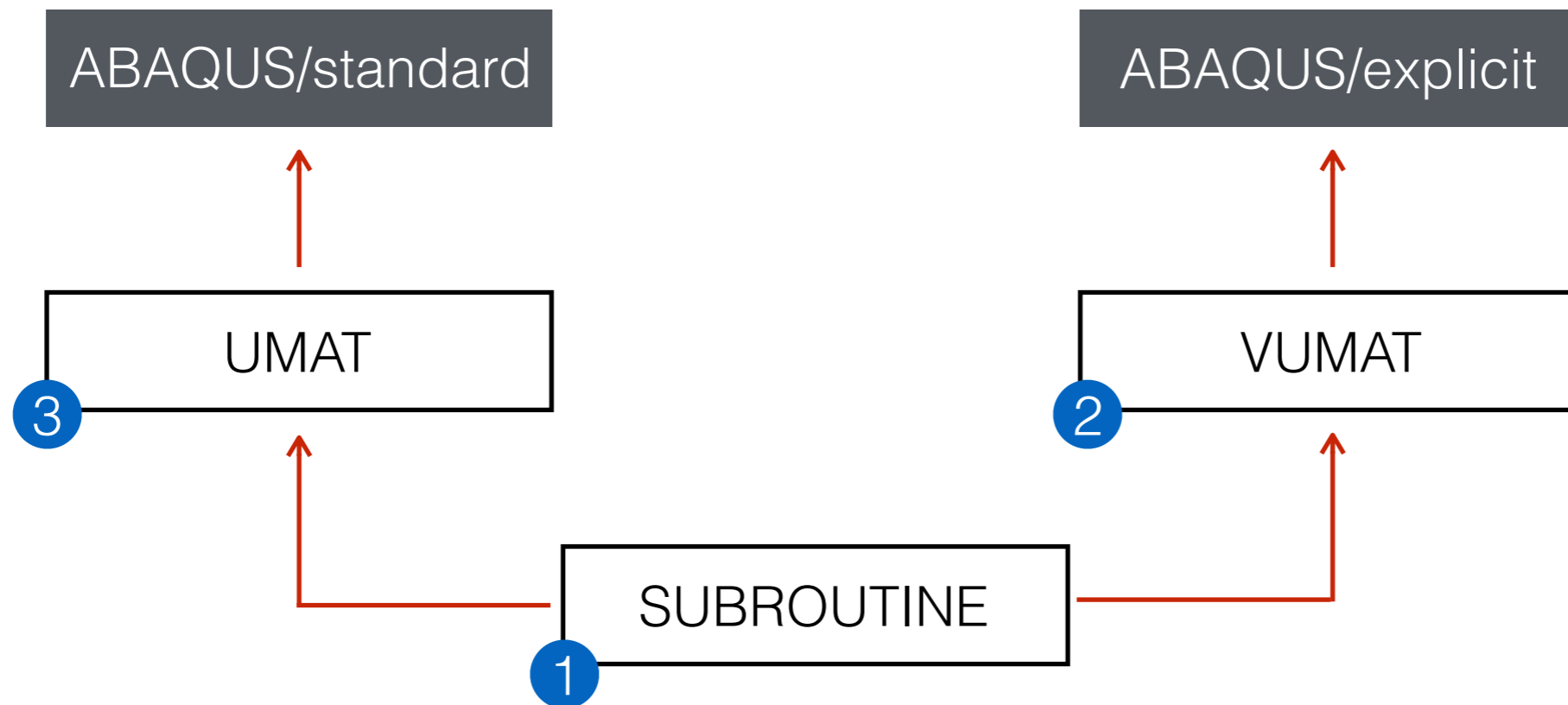
- l_e is the element characteristic length
- ρ is the density of the material
- E is the Young's modulus

Initialization step (elastic)

```
if((steptime.eq.totaltime).and.(steptime.eq.zero))then
  E0 = props(1)
  NU = props(2)
  BULK = E0/(3.0*(1.0-2.0*NU))
  R2G = E0/(1.0+NU)
  do i=1,NBLOCK
    if(NSHR.eq.3)then
      volstrain = STRAININC(i,1)+STRAININC(i,2)+STRAININC(i,3)
      STRESSNEW(i,1) = R2G*(STRAININC(i,1)-third*volstrain)
      + BULK*volstrain
      STRESSNEW(i,2) = R2G*(STRAININC(i,2)-third*volstrain)
      + BULK*volstrain
      STRESSNEW(i,3) = R2G*(STRAININC(i,3)-third*volstrain)
      + BULK*volstrain
      STRESSNEW(i,4) = R2G*STRAININC(i,4)
      STRESSNEW(i,5) = R2G*STRAININC(i,5)
      STRESSNEW(i,6) = R2G*STRAININC(i,6)
    else
      volstrain = STRAININC(i,1)+STRAININC(i,2)+STRAININC(i,3)
      STRESSNEW(i,1) = R2G*(STRAININC(i,1)-third*volstrain)
      + BULK*volstrain
      STRESSNEW(i,2) = R2G*(STRAININC(i,2)-third*volstrain)
      + BULK*volstrain
      STRESSNEW(i,3) = R2G*(STRAININC(i,3)-third*volstrain)
      + BULK*volstrain
      STRESSNEW(i,4) = R2G*STRAININC(i,4)
    endif
  enddo
```

(V)UMAT subroutine

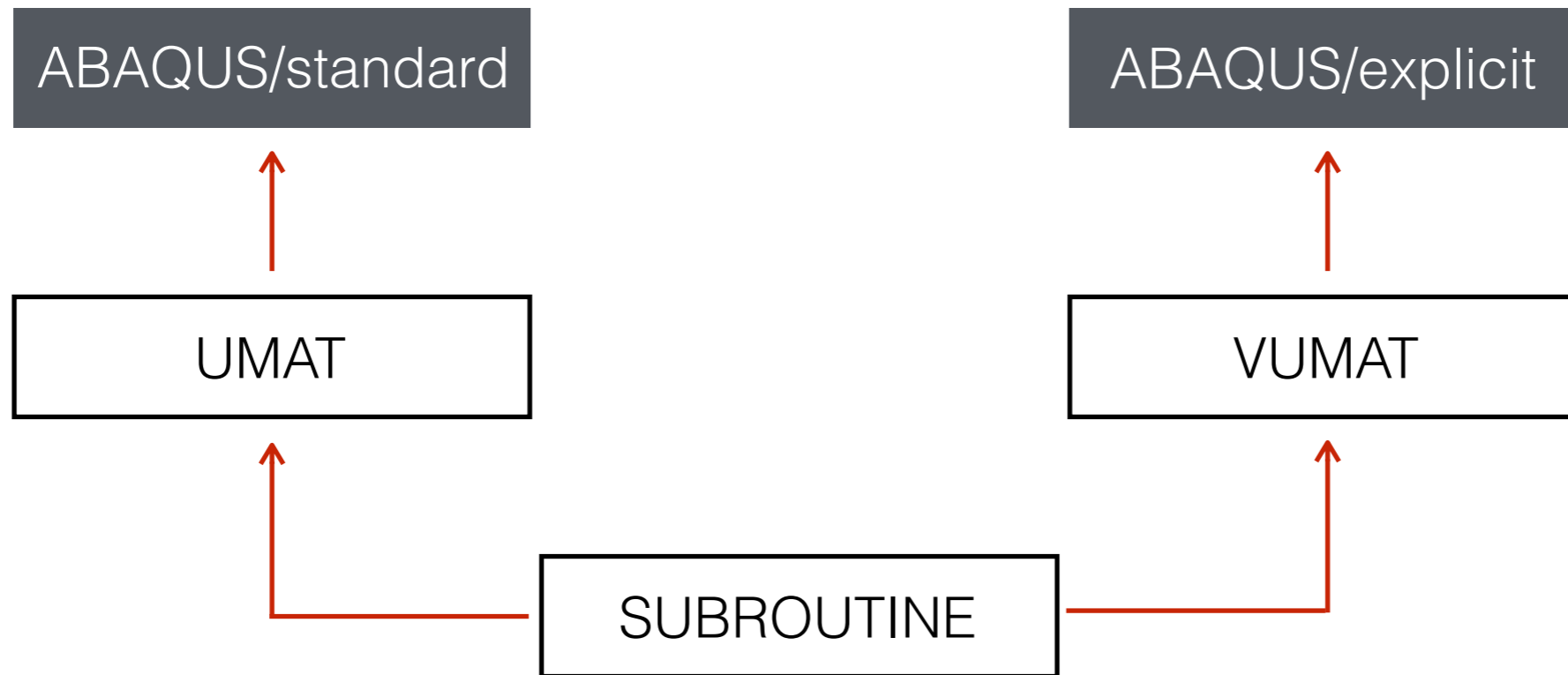
A simplified approach to UMAT/VUMAT coding:



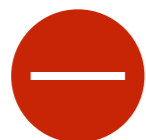
- 1 Code and compile the material model in FORTRAN
- 2 Link the code to the VUMAT subroutine
- 3 Link the code to the UMAT subroutine

(V)UMAT subroutine

A simplified approach to UMAT/VUMAT coding:



- Easier to debug
- A model available in both ABAQUS/standard and explicit



- Less efficient code

(V)UMAT subroutine

ABAQUS/standard

- Include a subroutine with the code
- Send data to the subroutine

```
INCLUDE './UMAT_MODEL.f'  
  
SUBROUTINE UMAT(STRESS, STATEV, DDSDDDE, SSE, SPD, SCD,  
+             RPL, DDSDDT, DRPLDE, DRPLDT,  
+             STRAN, DSTRAN, TIMEA, DTIMEA, TEMP, DTEMP, PREDEF, DPRED,  
+             CMNAME, NDI, NSHR, NTENS, NSTATV, PROPS, NPROPS, COORDS,  
+             DROT, PNEWDT, CELENT, DFGRD0, DFGRD1, NOEL, NPT, LAYER,  
+             KSPT, KSTEP, KINC)  
INCLUDE 'ABA_PARAM.INC'  
  
!-----Declaration ABAQUS variables  
  
character*80 CMNAME  
DIMENSION STRESS(NTENS), STATEV(NSTATV), DDSDDDE(NTENS,NTENS),  
+         DDSDDT(NTENS), DRPLDE(NTENS), STRAN(NTENS), DSTRAN(NTENS),  
+         TIMEA(2), PREDEF(1), DPRED(1), PROPS(NPROPS), COORDS(3),  
+         DROT(3,3), DFGRD0(3,3), DFGRD1(3,3)  
  
! Call UMAT_MODEL  
  
call UMAT_MODEL(DDSDDDE, STRESS, STATEV, DSTRAN, PROPS,  
+             KINC, NTENS, NSTATV, NPROPS)  
  
! End of subroutine  
  
return  
end
```

(V)UMAT subroutine

ABAQUS/explicit

- Include a subroutine with the code
- Send data to the subroutine
- Vectorized to scalar
- Tensor ordering

```
INCLUDE './UMAT_MODEL.f'
```

```
SUBROUTINE VUMAT(  
+ NBLOCK, NDIR, NSHR, NSTATEV, NFIELDV, NPROPS, LANNEAL, STEPTIME,  
+ TOTALTIME, DT, CMNAME, COORDMP, CHARLENGTH, PROPS, DENSITY,  
+ STRAININC, RELSPININC, TEMPOLD, STRETCHOLD, DEFGRADOLD, FIELDoLD,  
+ STRESSOLD, STATEOLD, ENERINTERNOLD, ENERINELASOLD, TEMPNEW,  
+ STRETCHNEW, DEFGRADNEW, FIELDNEW,  
+ STRESSNEW, STATENEW, ENERINTERNNEW, ENERINELASNEW)  
C  
C  
C
```

```
GRAB HISTORY VARIABLES
```

```
do k=1,NSTATEV  
STATEEV(k) = STATEOLD(i,k)  
enddo
```

```
CALL UMAT_MODEL
```

```
+ call UMAT_MODEL(DDSDDE, STRESS, STATEEV, DSTRAN, PROPS2,  
KINC, NTENS, NSTATV, NPROPS)
```

```
UNPACK STRESSES
```

```
STRESSNEW(i,1) = STRESS(1)  
STRESSNEW(i,2) = STRESS(2)  
STRESSNEW(i,3) = STRESS(3)  
STRESSNEW(i,4) = STRESS(4)  
if(NSHR.eq.3)then  
STRESSNEW(i,6) = STRESS(5)  
STRESSNEW(i,5) = STRESS(6)  
endif
```

```
GRAB STRAININC
```

```
DSTRAN(1) = STRAININC(i,1)  
DSTRAN(2) = STRAININC(i,2)  
DSTRAN(3) = STRAININC(i,3)  
DSTRAN(4) = 2.0*STRAININC(i,4)  
if(NSHR.eq.3)then  
DSTRAN(5) = 2.0*STRAININC(i,6)  
DSTRAN(6) = 2.0*STRAININC(i,5)  
endif
```

(V)UMAT subroutine

The same material card input can be used between ABAQUS/Standard and ABAQUS/Explicit

ABAQUS/explicit

```
**-----  
** MATERIALS  
**-----  
*material,name=EXAMPLE_VUMAT  
*density  
7.8e-9  
*user material, CONSTANTS=24  
**      E,      NU, BLANK, BLANK, BLANK, BLANK, BLANK, BLANK  
| 21000.0,    0.3,  0.0,  0.0,  0.0,  0.0,  0.0,  0.0  
** SIGMA0,    T1,  Q1,   T2,   Q2,   T3,   Q3, BLANK  
| 250.0, 10000.0, 10.0, 1000.0, 100.0, 100.0, 1000.0,  0.0  
**      WC,  DCRIT, BLANK, BLANK, BLANK, BLANK, BLANK, BLANK  
| 100.0,    1.0  
*depvar, delete=3  
3  
1, P, "Equivalent plastic strain"  
2, D, "Damage"  
3,STATUS, "Status variable"  
**-----
```

ABAQUS/standard

```
**-----  
** MATERIALS  
**-----  
*material,name=EXAMPLE_UMAT  
*user material, CONSTANTS=24  
**      E,      NU, BLANK, BLANK, BLANK, BLANK, BLANK, BLANK  
| 21000.0,    0.3,  0.0,  0.0,  0.0,  0.0,  0.0,  0.0  
** SIGMA0,    T1,  Q1,   T2,   Q2,   T3,   Q3, BLANK  
| 250.0, 10000.0, 10.0, 1000.0, 100.0, 100.0, 1000.0,  0.0  
**      WC,  DCRIT, BLANK, BLANK, BLANK, BLANK, BLANK, BLANK  
| 100.0,    1.0  
*depvar, delete=3  
3  
1, P, "Equivalent plastic strain"  
2, D, "Damage"  
3,STATUS, "Status variable"  
**-----
```

(V)UMAT subroutine

In this example, we want to develop an elasto-plastic model with a ductile fracture model.

Hypo-elasticity:

$$\hat{\mathbf{D}} = \hat{\mathbf{D}}_e + \hat{\mathbf{D}}_p$$

Isotropic elastic:

$$\dot{\hat{\boldsymbol{\sigma}}} = \frac{E}{1 + \nu} \hat{\mathbf{D}}'_e + \frac{E}{3(1 - 2\nu)} \text{tr} \hat{\mathbf{D}}_e \mathbf{I}$$

Yield function:

$$f = \sigma_{eq} - \sigma_y$$

Associated plastic flow:

$$\hat{\mathbf{D}}_p = \dot{\lambda} \frac{\partial f}{\partial \hat{\boldsymbol{\sigma}}}$$

Equivalent stress:

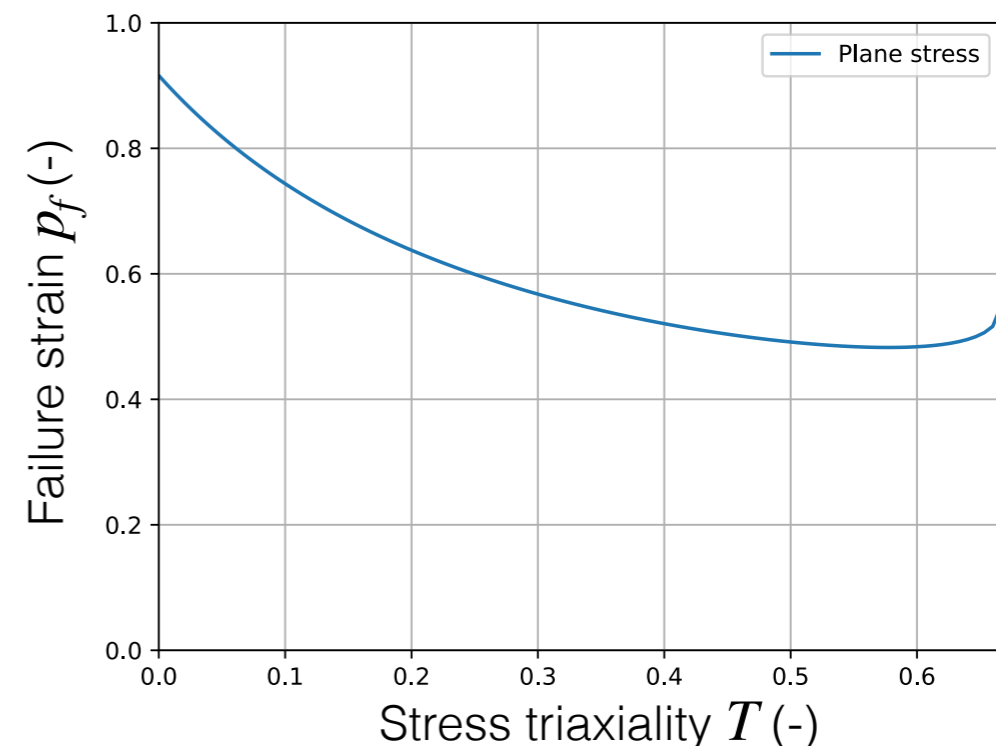
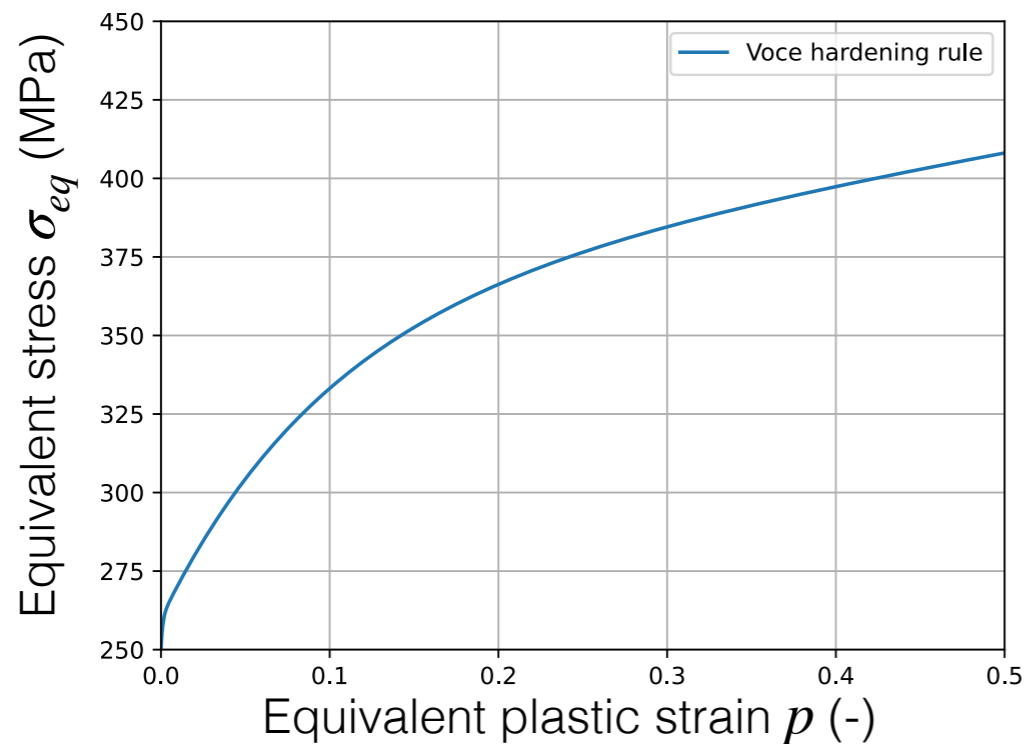
$$\sigma_{eq} = \sqrt{3J_2}$$

Isotropic hardening:

$$\sigma_y = \sigma_0 + \sum_{i=1}^3 Q_i \left(1 - \exp \left(-\frac{\theta_i}{Q_i} p \right) \right)$$

Damage indicator model:

$$D = \int_0^{p_f} \frac{\langle \sigma_1 \rangle}{W_c} dp \leq D_c$$



(V)UMAT subroutine

Computational plasticity:

1) Elastic prediction

$$\hat{\boldsymbol{\sigma}}^{TRIAL} = \hat{\boldsymbol{\sigma}}^t + \hat{\mathbf{C}}_e : \hat{\mathbf{D}}^{(t+\Delta t)} \Delta t$$

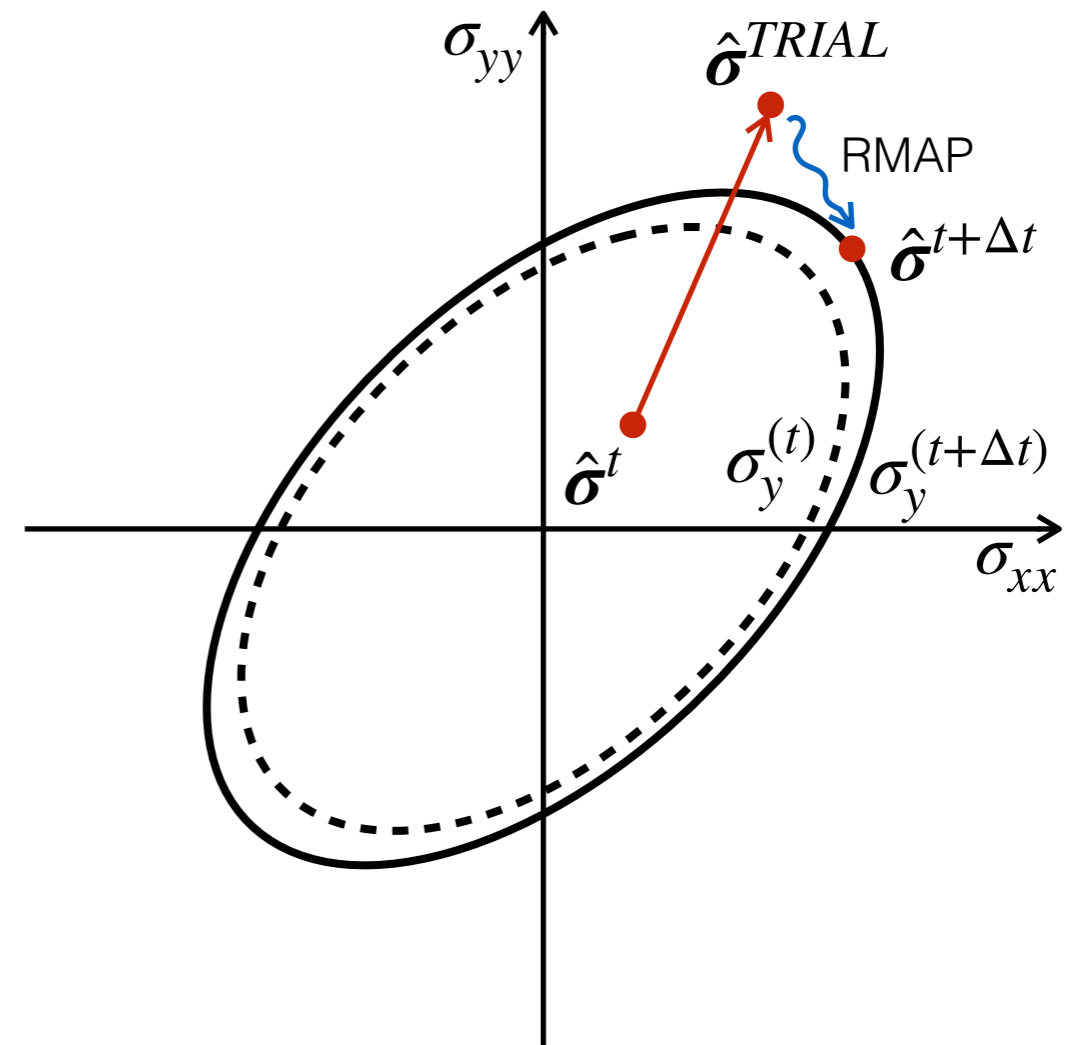
2) Compute yield function

$$f = \sigma_{eq}(\hat{\boldsymbol{\sigma}}^{TRIAL}) - \sigma_y^{(t)}$$

3) Check yield function

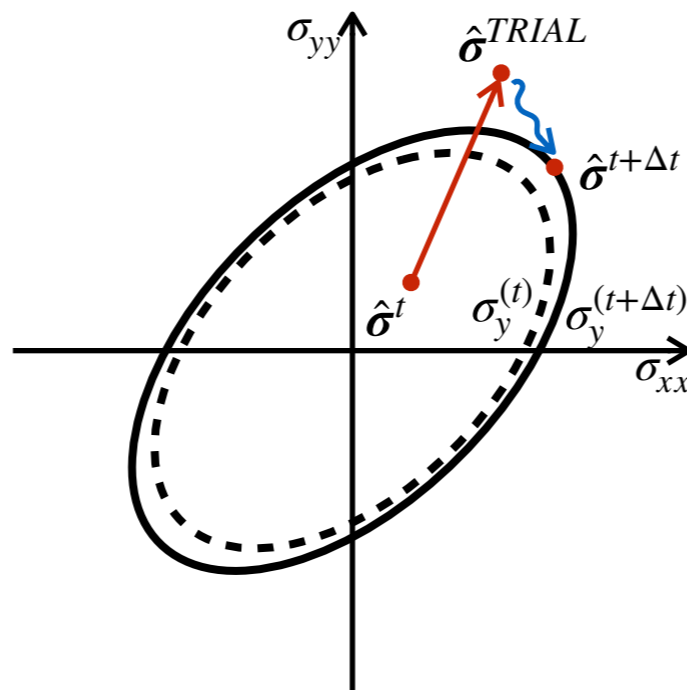
If $f < 0 \longrightarrow \hat{\boldsymbol{\sigma}}^{t+\Delta t} = \hat{\boldsymbol{\sigma}}^{TRIAL}$

If $f \geq 0 \longrightarrow$ Solve the non-linear system of equations (RMAP)

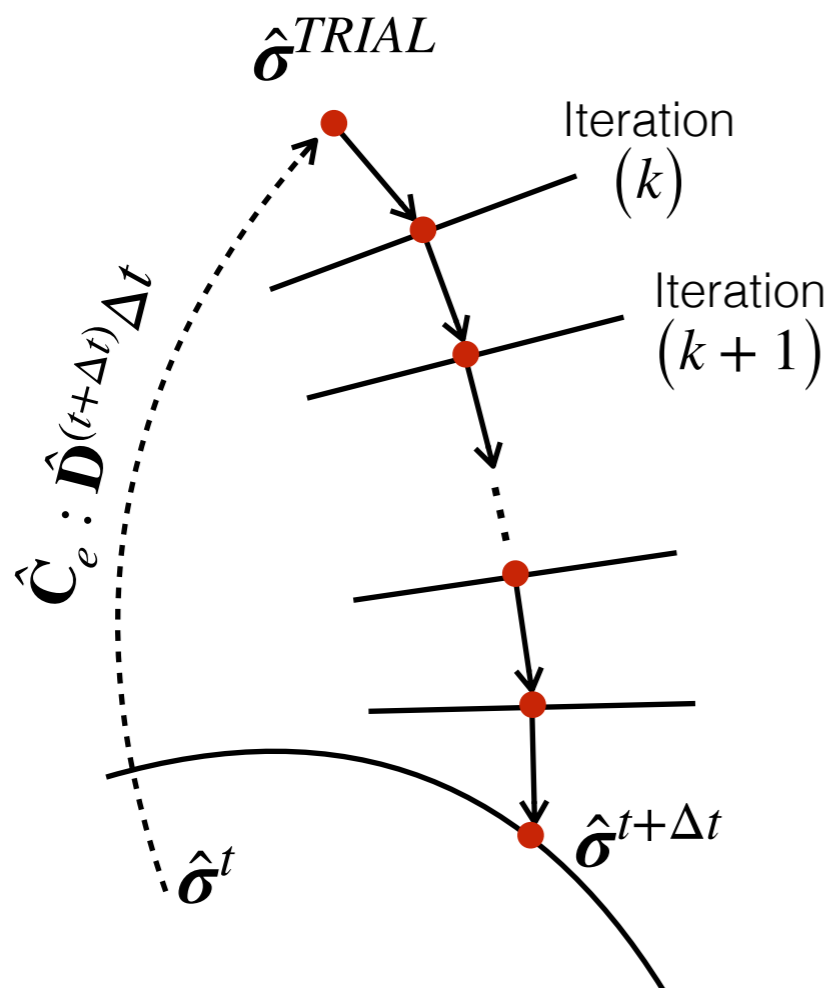


(V)UMAT subroutine

Return Map Algorithm (RMAP):



Cutting-plane algorithm:



Linearisation of the yield surface: $f(\hat{\sigma})|_{k+1} = 0$

$$\delta\lambda^{(k+1)} = \frac{f(\hat{\sigma})|_k}{\frac{\partial f}{\partial \hat{\sigma}}|_k : \mathbf{C}_e : \frac{\partial f}{\partial \hat{\sigma}}|_k - \frac{\partial f}{\partial \sigma_y}|_k \frac{\partial \sigma_y}{\partial \lambda}|_k}$$

$$\hat{\sigma}^{(k+1)} = \hat{\sigma}^{(k)} - \delta\lambda \hat{\mathbf{C}}_e : \frac{\partial f}{\partial \hat{\sigma}}$$

$$\sigma_y^{(k+1)} = \sigma_y^{(k)} - \delta\lambda \frac{\partial f}{\partial \lambda}$$

(V)UMAT subroutine

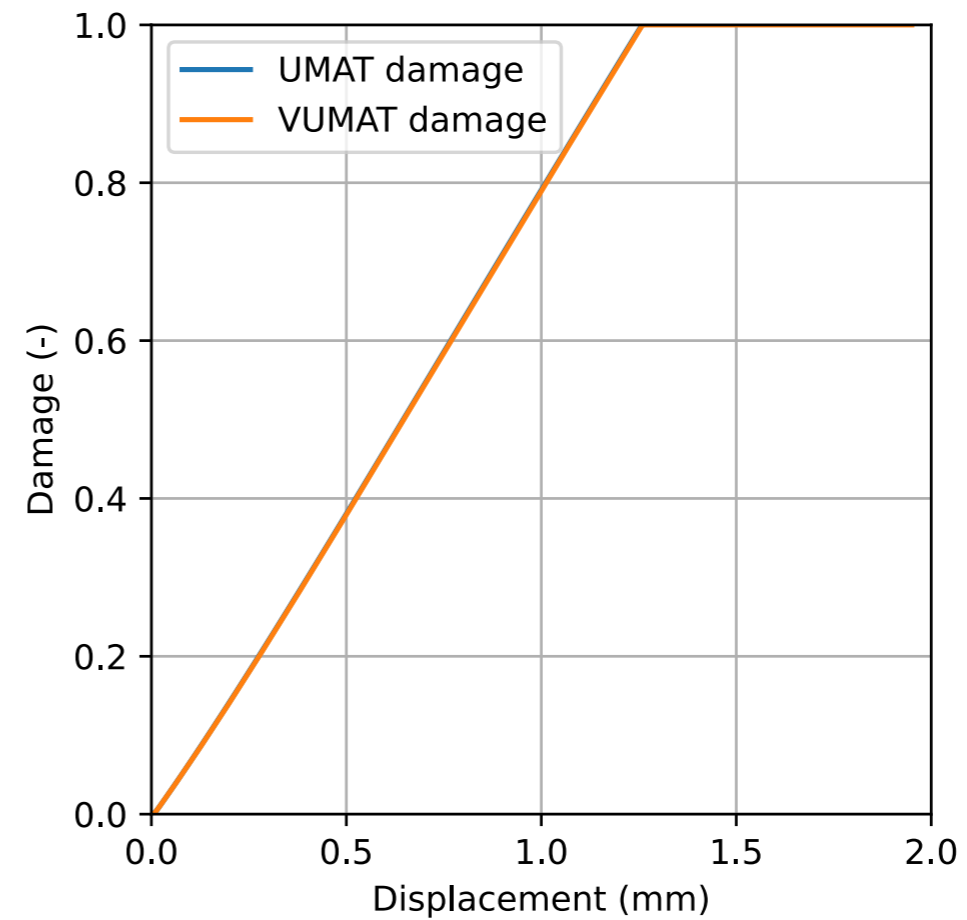
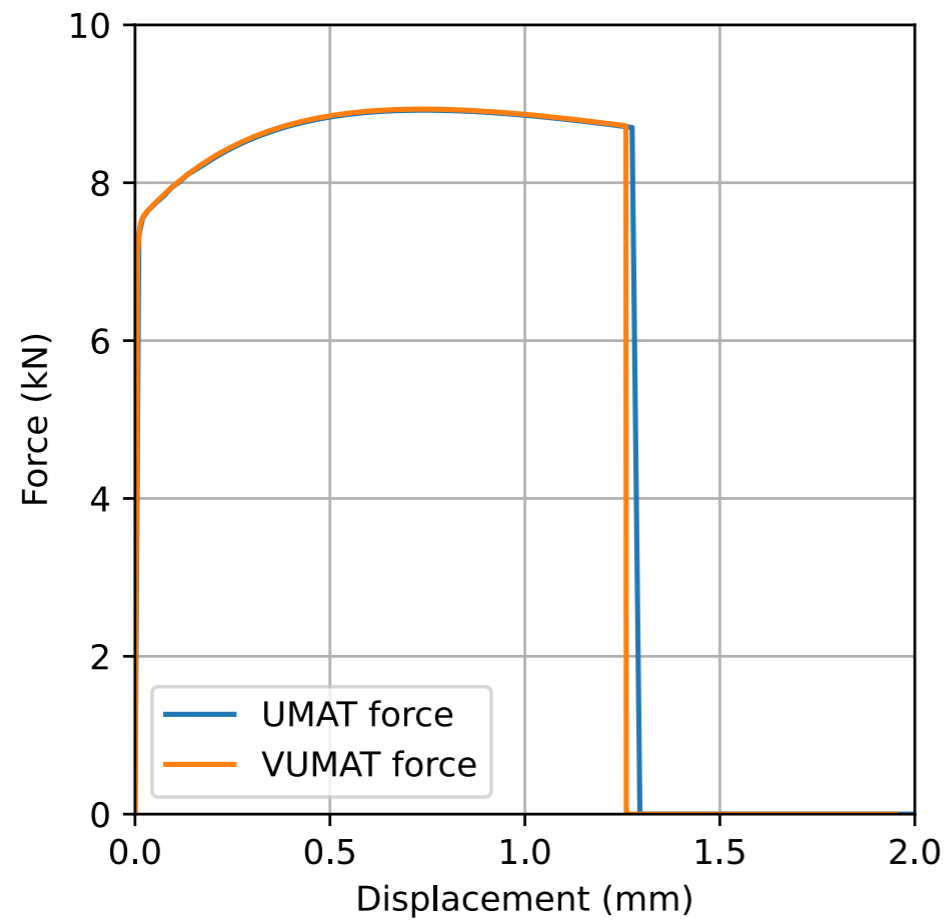
UMAT_MODEL.f quick description:

```
!-----  
!-----Declaration internal variables  
!-----  
integer i,j  
!DECLARE -- Strain increments  
real*8 d1,d2,d3,d4,d5,d6  
!DECLARE -- Stress tensor components  
real*8 s1,s2,s3,s4,s5,s6  
!DECLARE -- Old stress tensor components  
real*8 s1old,s2old,s3old,s4old,s5old,s6old  
!DECLARE -- Trial stress tensor components  
real*8 t1,t2,t3,t4,t5,t6  
!DECLARE -- Equivalent plastic strain  
real*8 p,pold  
!DECLARE -- Elasticity constants  
real*8 E0,NU  
!DECLARE -- Elasticity matrix  
real*8 Ce(6,6)  
!DECLARE -- Yield surface parameters  
real*8 SIGMAY,dSIGMAYdp  
!DECLARE -- Yield function  
real*8 YF  
!DECLARE -- Equivalent stress  
real*8 PHI  
!DECLARE -- Yield function derivatives  
real*8 dfds1,dfds2,dfds3,dfds4,dfds5,dfds6,con  
real*8 dyfds,dyfdL,dfdSY  
!DECLARE -- Work-hardening parameters  
real*8 SIGMA0,TR1,QR1,TR2,QR2,TR3,QR3  
real*8 T1oQ1,T2oQ2,T3oQ3
```

```
! Extract history variables  
  
pold = STATEV(1)  
damageold = STATEV(2)  
  
! Compute elastic prediction  
  
t1 = s1old+(Ce(1,1)*d1+Ce(1,2)*d2+Ce(1,3)*d3)  
t2 = s2old+(Ce(2,1)*d1+Ce(2,2)*d2+Ce(2,3)*d3)  
t3 = s3old+(Ce(3,1)*d1+Ce(3,2)*d2+Ce(3,3)*d3)  
t4 = s4old+(Ce(4,4)*d4)  
t5 = s5old+(Ce(5,5)*d5)  
t6 = s6old+(Ce(6,6)*d6)  
  
! Compute equivalent stress  
  
PHI = (t1*t1+t2*t2+t3*t3-t1*t2-t2*t3-t3*t1  
+ 3.0*(t4*t4+t5*t5+t6*t6))  
if(PHI.gt.0.0)then  
| PHI = sqrt(PHI)  
else  
| PHI = 0.0  
endif  
  
! Compute Yield stress  
  
SIGMAY = SIGMA0+QR1*(1.0-exp(-T1oQ1*pold))  
+ QR2*(1.0-exp(-T2oQ2*pold))  
+ QR3*(1.0-exp(-T3oQ3*pold))  
  
! Compute Yield function  
  
YF = PHI-SIGMAY  
  
! CHECK FOR PLASTICITY  
  
IF(YF.lt.0.0)THEN! ELASTICITY
```

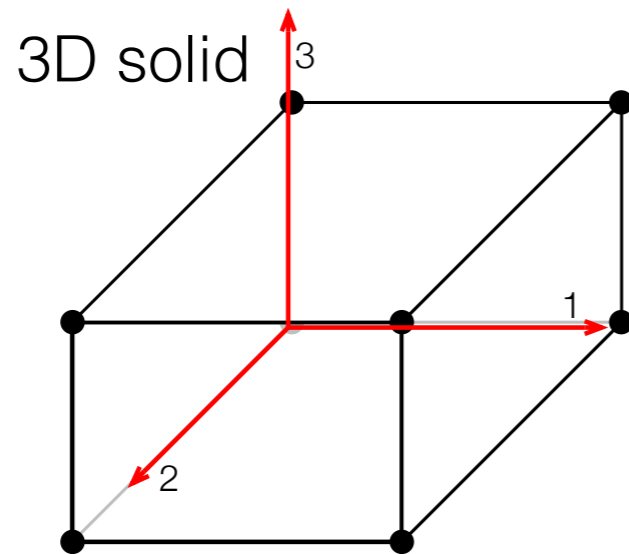
(V)UMAT subroutine

Results from the UMAT and VUMAT subroutines

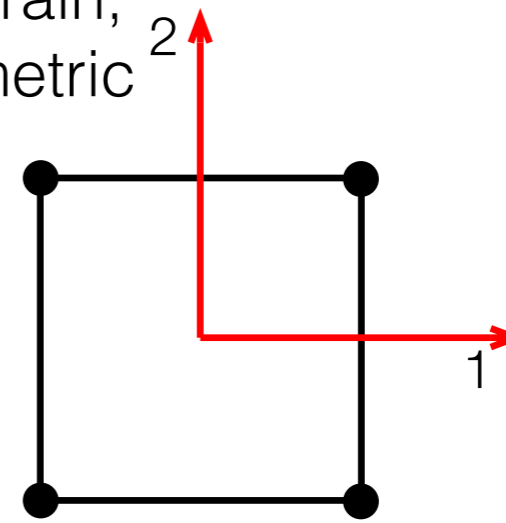


(V)UMAT subroutine

The UMAT and VUMAT subroutines should work for:



2D plane strain,
2D axisymmetric



Stress tensor:

$$\boldsymbol{\sigma} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{12} & \sigma_{22} & \sigma_{23} \\ \sigma_{23} & \sigma_{13} & \sigma_{33} \end{bmatrix}$$

Stress tensor:

$$\boldsymbol{\sigma} = \begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{12} & \sigma_{22} \end{bmatrix}$$

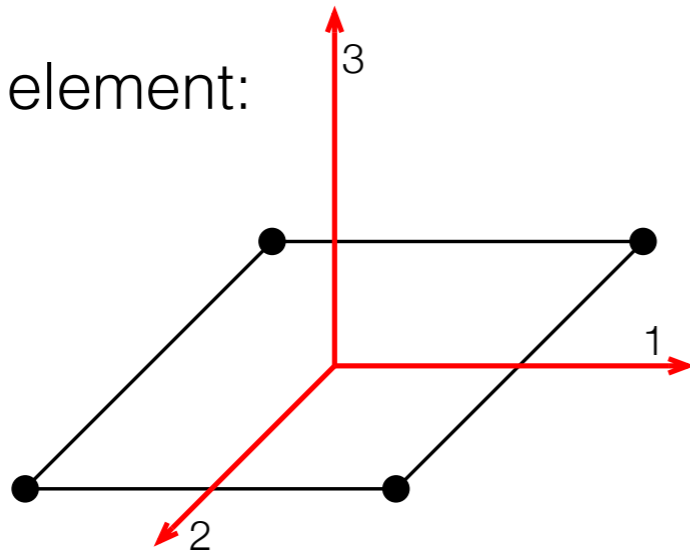
VUMAT

```
STRESS(1) = STRESSOLD(i,1)
STRESS(2) = STRESSOLD(i,2)
STRESS(3) = STRESSOLD(i,3)
STRESS(4) = STRESSOLD(i,4)
if(NSHR.eq.3)then
  STRESS(5) = STRESSOLD(i,6)
  STRESS(6) = STRESSOLD(i,5)
endif
```

```
DSTRAN(1) = STRAININC(i,1)
DSTRAN(2) = STRAININC(i,2)
DSTRAN(3) = STRAININC(i,3)
DSTRAN(4) = 2.0*STRAININC(i,4)
if(NSHR.eq.3)then
  DSTRAN(5) = 2.0*STRAININC(i,6)
  DSTRAN(6) = 2.0*STRAININC(i,5)
endif
```

(V)UMAT subroutine

Shell element:



Plane stress hypothesis:

$$\sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13}^e \\ \sigma_{12} & \sigma_{22} & \sigma_{23}^e \\ \sigma_{23}^e & \sigma_{13}^e & 0 \end{bmatrix}$$

Through-thickness shear stresses handled externally as elastic

```

**-----
*material,name=EXAMPLE_VUMAT_SHELL
*density
7.8e-9
*user material, CONSTANTS=24
**      E,      NU, BLANK, BLANK, BLANK, BLANK, BLANK, BLANK
| 210000.0,    0.3,  0.0,  0.0,  0.0,  0.0,  0.0,  0.0
** SIGMA0,    T1,  Q1,   T2,   Q2,   T3,   Q3,  BLANK
| 250.0, 10000.0, 10.0, 1000.0, 100.0, 100.0, 1000.0,  0.0
**      WC,    DCRIT, BLANK, BLANK, BLANK, BLANK, BLANK, BLANK
| 250.0,    1.0
*Transverse Shear
6730.7,6730.7, 0
*depvar, delete=3
3
1, P, "Equivalent plastic strain"
2, D, "Damage"
3,STATUS, "Status variable"
**-----
    
```

Transverse shear stiffnesses: K_{11}, K_{22}, K_{12}

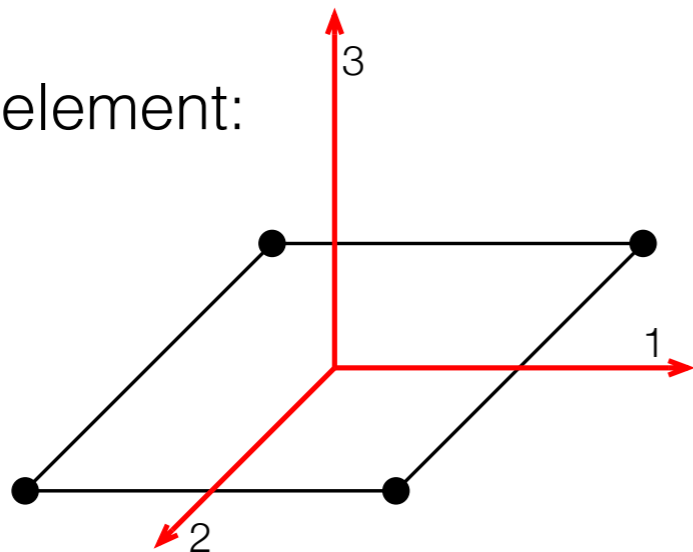
$$K_{11} = K_{22} = \frac{5}{6} G t_0$$

where G is the shear modulus and t_0 is the initial thickness of the shell element.

$$K_{12} = 0$$

(V)UMAT subroutine

Shell element:



Plane stress hypothesis:

$$\boldsymbol{\sigma} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13}^e \\ \sigma_{12} & \sigma_{22} & \sigma_{23}^e \\ \sigma_{23}^e & \sigma_{13}^e & \boxed{0} \end{bmatrix}$$

Through-thickness stress $\sigma_{33} = 0$

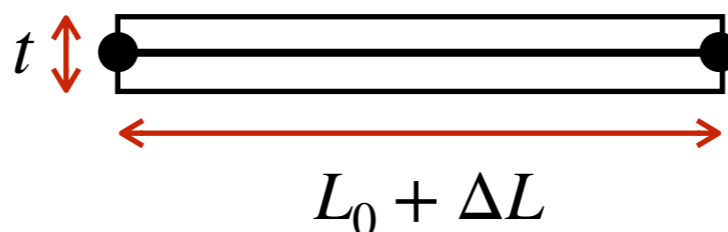
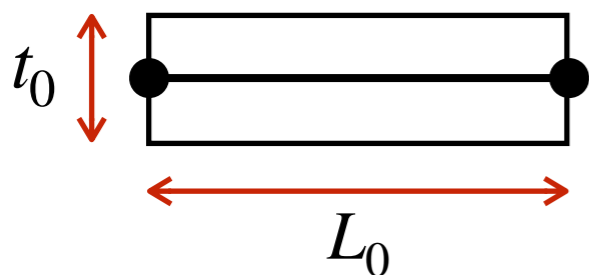
Plane stress hypothesis: $\sigma_{33} = 0$

```

!-----
c      UNPACK STRESSES
!-----
STRESSNEW(i,1) = STRESS(1)
STRESSNEW(i,2) = STRESS(2)
STRESSNEW(i,3) = 0.0
STRESSNEW(i,4) = STRESS(4)
STRAININC(i,3) = DSTRAN(3)
    
```

Thickness change: $\Delta \epsilon_{33}$

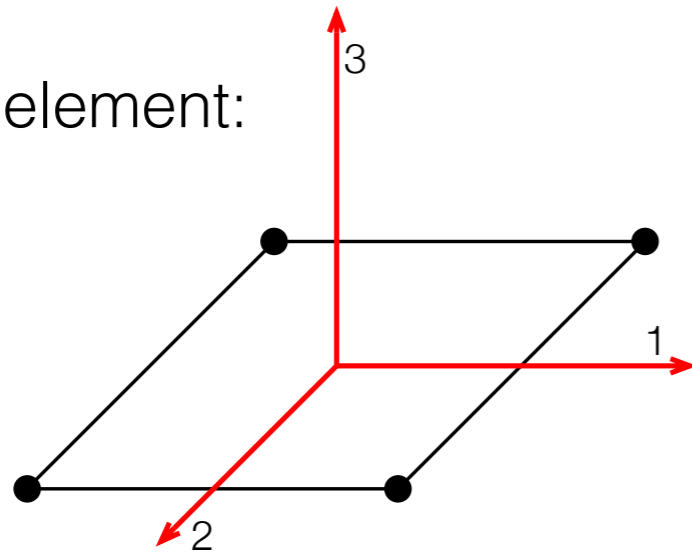
Thickness change:



$$t = t_0 \exp(\epsilon_{33})$$

(V)UMAT subroutine

Shell element:



$$\boldsymbol{\sigma} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13}^e \\ \sigma_{12} & \sigma_{22} & \sigma_{23}^e \\ \sigma_{23}^e & \sigma_{13}^e & 0 \end{bmatrix}$$

Through-thickness stress $\sigma_{33} = 0$

Enforcing plane stress in a VUMAT:

- 1 Reformulate all constitutive equations according to plane stress hypothesis
- 2 Use 3D constitutive equations and iterate to enforce plane stress hypothesis

(V)UMAT subroutine

- 2 Use 3D constitutive equations and iterate to enforce plane stress hypothesis

Iteration 1

Assume elastic response

$$\Delta \varepsilon_{33} = -\frac{\nu}{1-\nu} (\Delta \varepsilon_{11} + \Delta \varepsilon_{22})$$

Compute $\sigma^{t+\Delta t}$, store $\Delta \varepsilon_{33}$ and σ_{33}

Iteration 2

Assume plastic incompressibility

$$\Delta \varepsilon_{33} = -(\Delta \varepsilon_{11} + \Delta \varepsilon_{22})$$

Compute $\sigma^{t+\Delta t}$, store $\Delta \varepsilon_{33}$ and σ_{33}

Use a secant update for $\Delta \varepsilon_{33}$

$$\Delta \varepsilon_{33}|_n = \Delta \varepsilon_{33}|_{n-1} - H_t \cdot \sigma_{33}|_{n-1}$$

$$H_t = \frac{\Delta \varepsilon_{33}|_{n-1} - \Delta \varepsilon_{33}|_{n-2}}{\sigma_{33}|_{n-1} - \sigma_{33}|_{n-2}}$$

Iteration n

$$\Delta \varepsilon = \begin{bmatrix} \Delta \varepsilon_{11} & \Delta \varepsilon_{22} & \Delta \varepsilon_{33} & \Delta \varepsilon_{12} & 0 & 0 \end{bmatrix}^T$$

3D SUBROUTINE



$$\sigma = \begin{bmatrix} \sigma_{11} & \sigma_{22} & \sigma_{33} & \sigma_{12} & 0 & 0 \end{bmatrix}^T$$

$$\text{If } |\sigma_{33}| > \xi (|\sigma_{11}| + |\sigma_{22}| + |\sigma_{12}|)$$

ξ is a numerical tolerance ($1e^{-5}$)

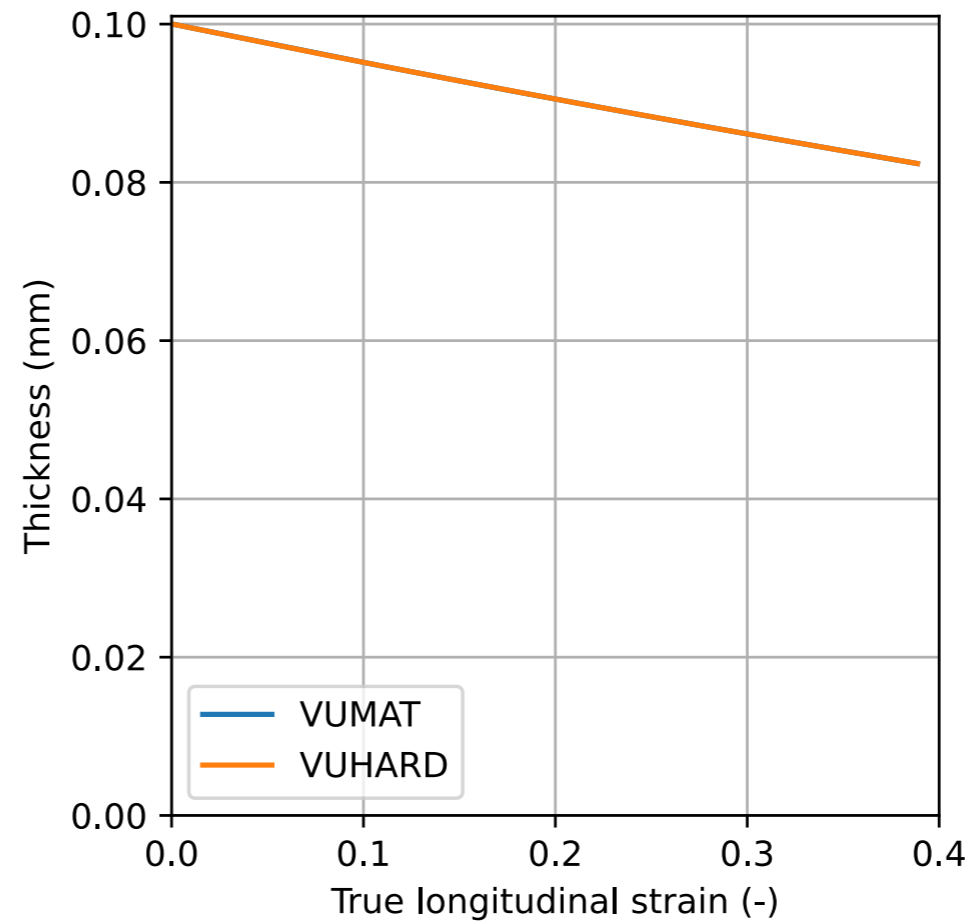
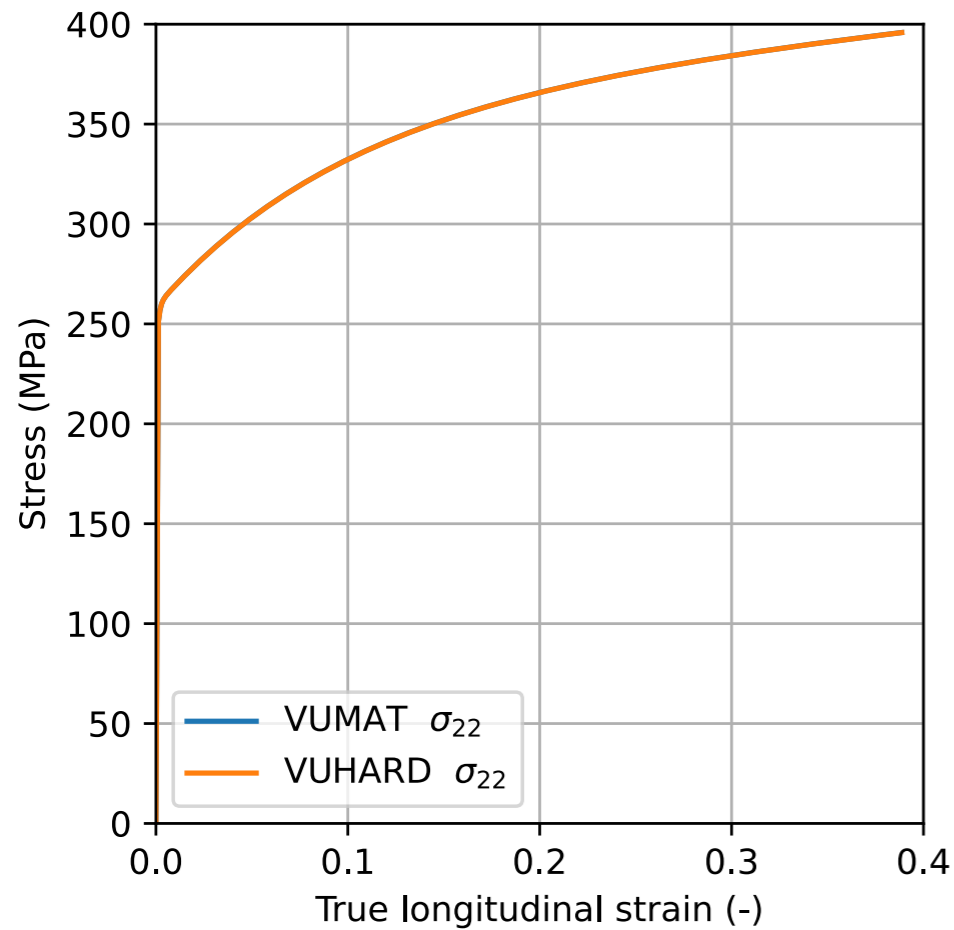
(V)UMAT subroutine

Enforcing plane stress in a VUMAT:

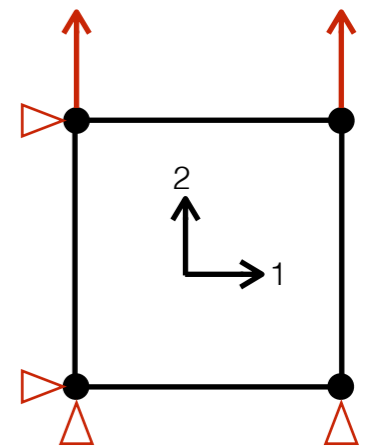
Method	1	2
	Computationally efficient	No need to change constitutive equations
	Constitutive equations only valid for plane stress	Computational cost

(V)UMAT subroutine

Using the VUMAT_SHELL.f subroutine and the VUHARD_V1.f subroutine:

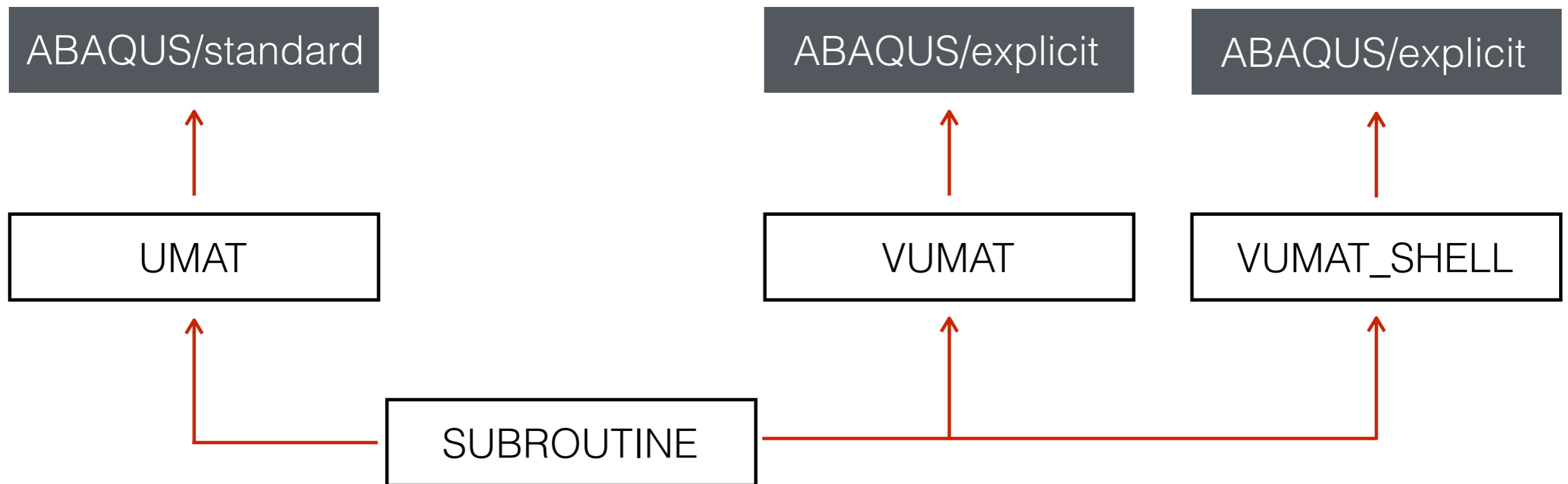


Single shell element in uniaxial tension

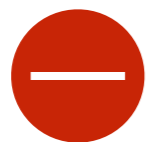


(V)UMAT subroutine

A simplified approach to UMAT/VUMAT coding:



- Easier to debug
- A model available in both ABAQUS/standard and explicit
- Both plane-stress and full 3D with one code



- Less efficient code

(V)UEXTERNALDB subroutine

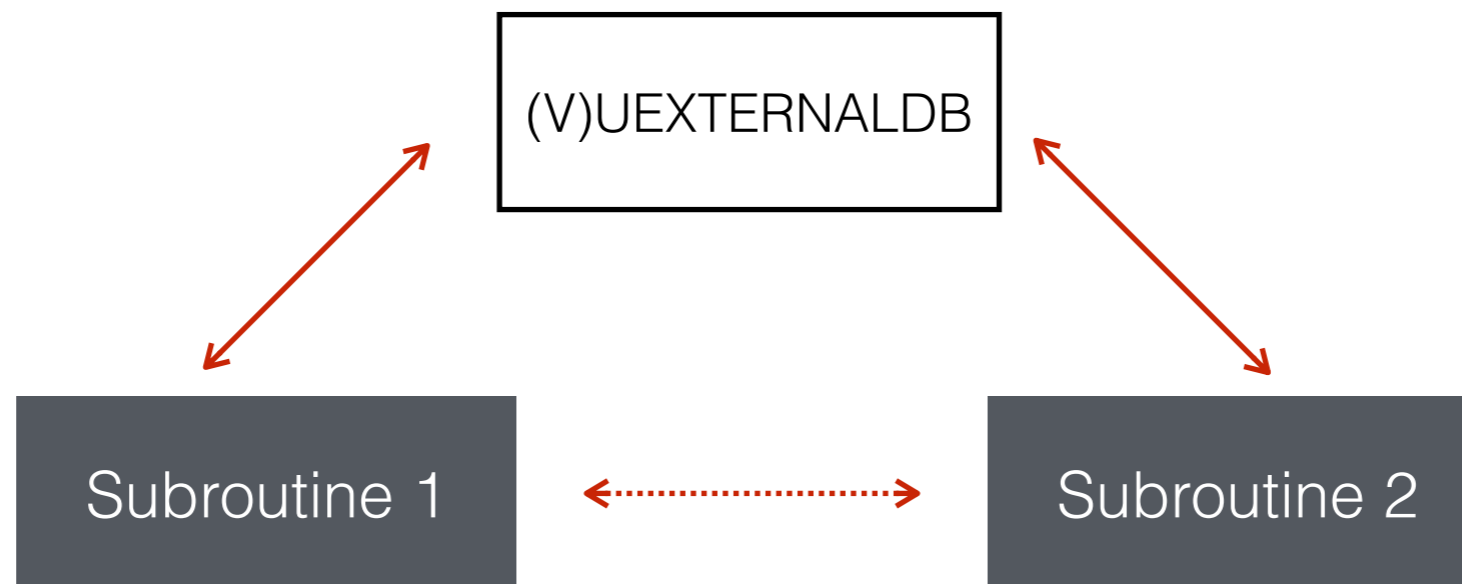
UEXTERNALDB: User subroutine to manage user-defined external databases and calculate model-independent history information.

VEXTERNALDB: User subroutine that gives control to the user at key moments of the analysis so that data can be exchanged dynamically among Abaqus user subroutines and with external programs or files.

(V)UEXTERNALDB subroutine

(V)UEXTERNALDB subroutines can be used to:

- Access external databases/files,
- Pass informations through the memory,
- Make computations which requires access to all integration points at once.



User subroutine **UEXTERNALDB**:

- is called **once** each at the **beginning of the analysis**, at the **beginning of each increment**, at the **end of each increment**, and at the end of the analysis (in addition, the user subroutine is also called once at the beginning of a restart analysis);

User subroutine **VEEXTERNALDB**:

- is called **once** at the **beginning of the analysis** at the beginning of each step, **before each increment**, at the start of **each increment**, at the **end** of each increment, at the end of each step, and finally at the end of the analysis;

(V)UEXTERNALDB subroutine

ABAQUS/standard

```
!-----  
!   Start of the analysis  
!-----  
!   if(LOP.eq.j_int_StartAnalysis)then  
!-----  
!   Start of the increment  
!-----  
!   elseif(LOP.eq.j_int_StartIncrement)then  
!-----  
!   End of the increment  
!-----  
!   elseif(LOP.eq.j_int_EndIncrement)then  
!-----  
!   End of the Analysis  
!-----  
!   elseif(LOP.eq.j_int_EndAnalysis)then  
!   endif  
!-----  
!   End of subroutine  
!-----  
!   RETURN  
!   END
```

ABAQUS/explicit

```
!-----  
!   Start of the analysis  
!-----  
!   if(l0p.eq.j_int_StartAnalysis)then  
!-----  
!   Setup of the increment  
!-----  
!   elseif(l0p.eq.j_int_SetupIncrement)then  
!-----  
!   Start of the increment  
!-----  
!   elseif(l0p.eq.j_int_StartIncrement)then  
!-----  
!   End of the increment  
!-----  
!   elseif(l0p.eq.j_int_EndIncrement)then  
!-----  
!   End of the analysis  
!-----  
!   elseif(l0p.eq.j_int_EndAnalysis)then  
!   endif  
!-----  
!   End of the subroutine  
!-----  
!   return  
!   end
```

(V)UEXTERNALDB subroutine

ABAQUS/standard

```
! Start of the analysis
!
! if(LOP.eq.j_int_StartAnalysis)then
!   IF((kInc.eq.0).and.(myThreadID.eq.0))THEN
!
!     CREATE GLOBAL ARRAYS
!
!     ptr_REAL = SMAFloatArrayCreate(ID_REAL, 24, 0.0)
```

↑ Pointer
 ↑ Pointer ID (unique number)
 ↑ Size
 ↑ Initial value

ABAQUS/explicit

```
! Start of the analysis
!
! if(lOp.eq.j_int_StartAnalysis)then
!   IF(kInc.eq.0)THEN
!
!     CREATE GLOBAL ARRAYS
!
!     ptr_REAL = SMAFloatArrayCreate(ID_REAL, 24, 0.0)
```

↑ Pointer
 ↑ Pointer ID (unique number)
 ↑ Size
 ↑ Initial value

1 Create float (real) array in memory

Define array size

Link pointer

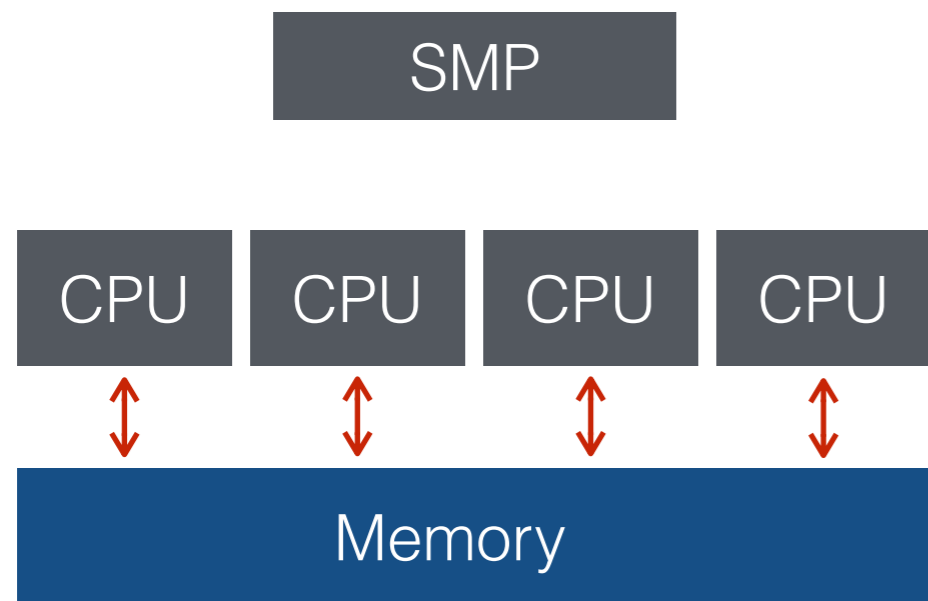
```
!-----Declare global variables
! REAL*8 PROPS_REAL(24) ! ARRAY WITH REAL PROPERTIES
! integer ID_REAL ! ID for pointers
! parameter(ID_REAL = 1) ! ID for pointers
! pointer(ptr_REAL, PROPS_REAL) ! pointer link
```

← Pointer ID

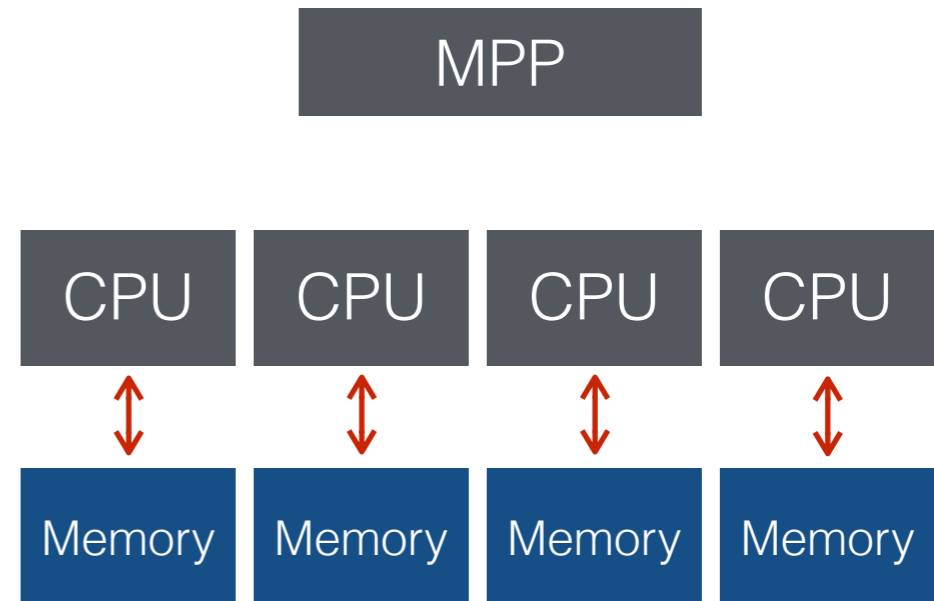
ENDIF

ENDIF

Interlude



CPUs share the same memory



CPUs have their own memory



CPUs have access to the same arrays

CPUs write in different arrays



CPUs have access to the same arrays

CPUs write in different arrays

Interlude

Should your code share the same arrays (for example non-local computations)?

YES

NO

SMP

It will natively do it, global arrays will work, You still need to prevent the code to write at the same place, check UEXTERNALDB.f for example.

```
!-----  
!   Get threadID  
!-----  
myThreadID = get_thread_id()  
IF((kInc.eq.0).and.(myThreadID.eq.0))THEN
```

Filter out threads



You need to define local arrays via:

```
!-----  
!   CREATE LOCAL ARRAYS  
!-----  
ptr_REAL = SMALocalFloatArrayCreate(ID_REAL, 24, 0.0)  
ptr_INT  = SMALocalIntArrayCreate( ID_INT, 24, 0)
```

Local arrays



MPP

You need to use MPI (Message Passing Interface) commands

Example:

```
call MPI_Bcast( N,size, MPI_INT,0, ABA_COMM_WORLD,ierr)  
call MPI_Bcast( W,size,MPI_DOUBLE_PRECISION,0, ABA_COMM_WORLD,ierr)
```

It will natively do it, global arrays will work

(V)UEL subroutine

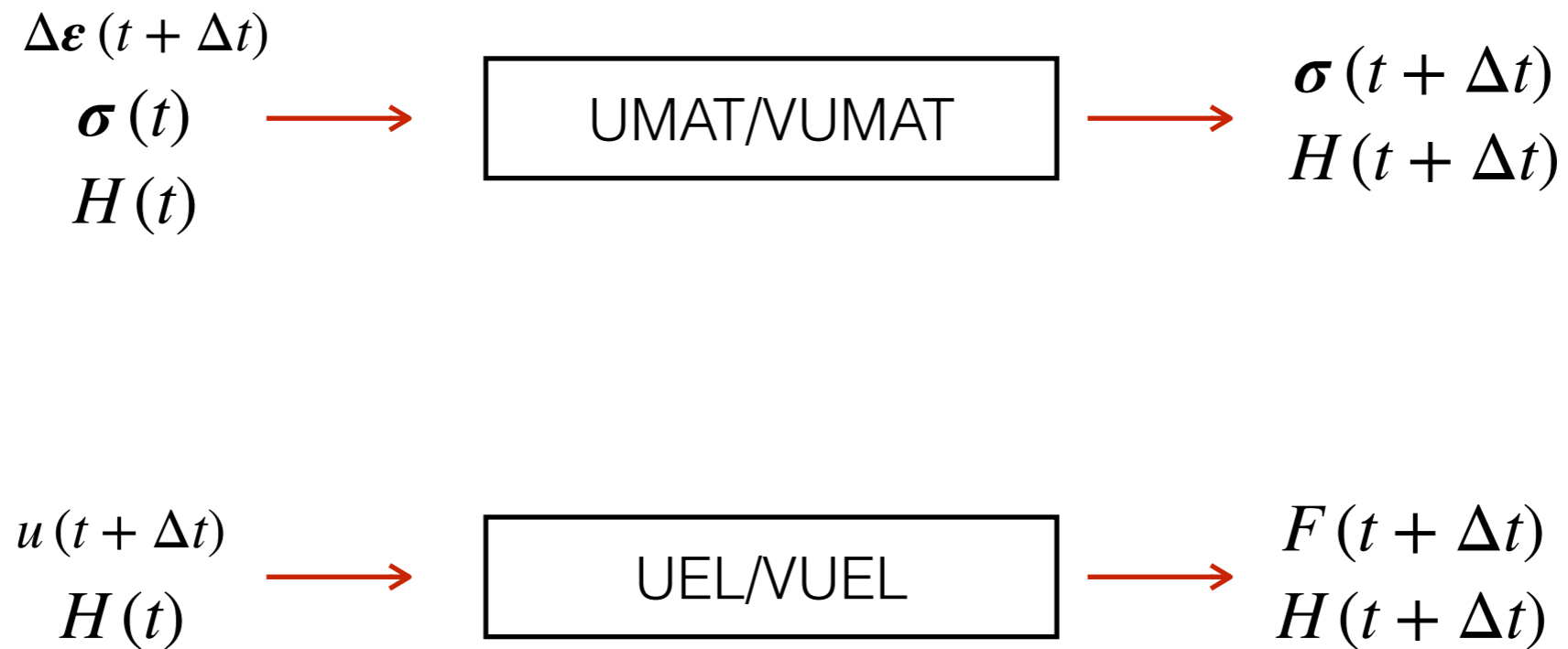
UEL: User subroutine to define an element.

WARNING: This feature is intended for advanced users only. Its use in all but the simplest test examples will require considerable coding by the user/developer. “User-defined elements,” Section 32.17.1 of the Abaqus Analysis User’s Guide, should be read before proceeding.

VUEL: User subroutine to define an element.

(V)UEL subroutine

Overall principle:



(V)UEL subroutine

```
Get Gauss points coordinates
call get_gauss_points(g,h,r,w,nint)

Get shape functions
call get_shape_functions(N,g,h,r,nnode,nint,eltype)

Get Jacobian functions
call get_jacobian_functions(J,detJ,g,h,r,position0,
+                          nint,ncoord,nnode,eltype)

Get derivatives of shape functions
call get_der_shape_functions(B,B2,J,g,h,r,
+                          nnode,ncoord,nint,eltype)

Compute strains in integration point
call compute_smallstrains(strain,B,U,
+                        ndof,ncoord,nnode,nint,eltype)

Compute strains in integration point
call compute_stresses(stress,CT,strain,dm,hisv,time,dt,
+                    nint,nhisv,ndof,eltype)

Update thickness
call update_thick(thick,strain,dm,
+               nint,ndof,ncoord,nnode,eltype)

Compute Internal forces
call compute_Fint(Fint,B,stress,w,detJ,thick,
+               nint,ndof,ncoord,nnode,eltype)

Compute Stiffness matrix
call compute_Kmatrix(Kmatrix,B,CT,w,DetJ,
+                  nint,nnode,ncoord,ndof,eltype)

Compute Mass matrix
call compute_Mmatrix(Mmatrix,rho,N,w,DetJ,
+                  nint,nnode,ncoord,ndof,eltype)

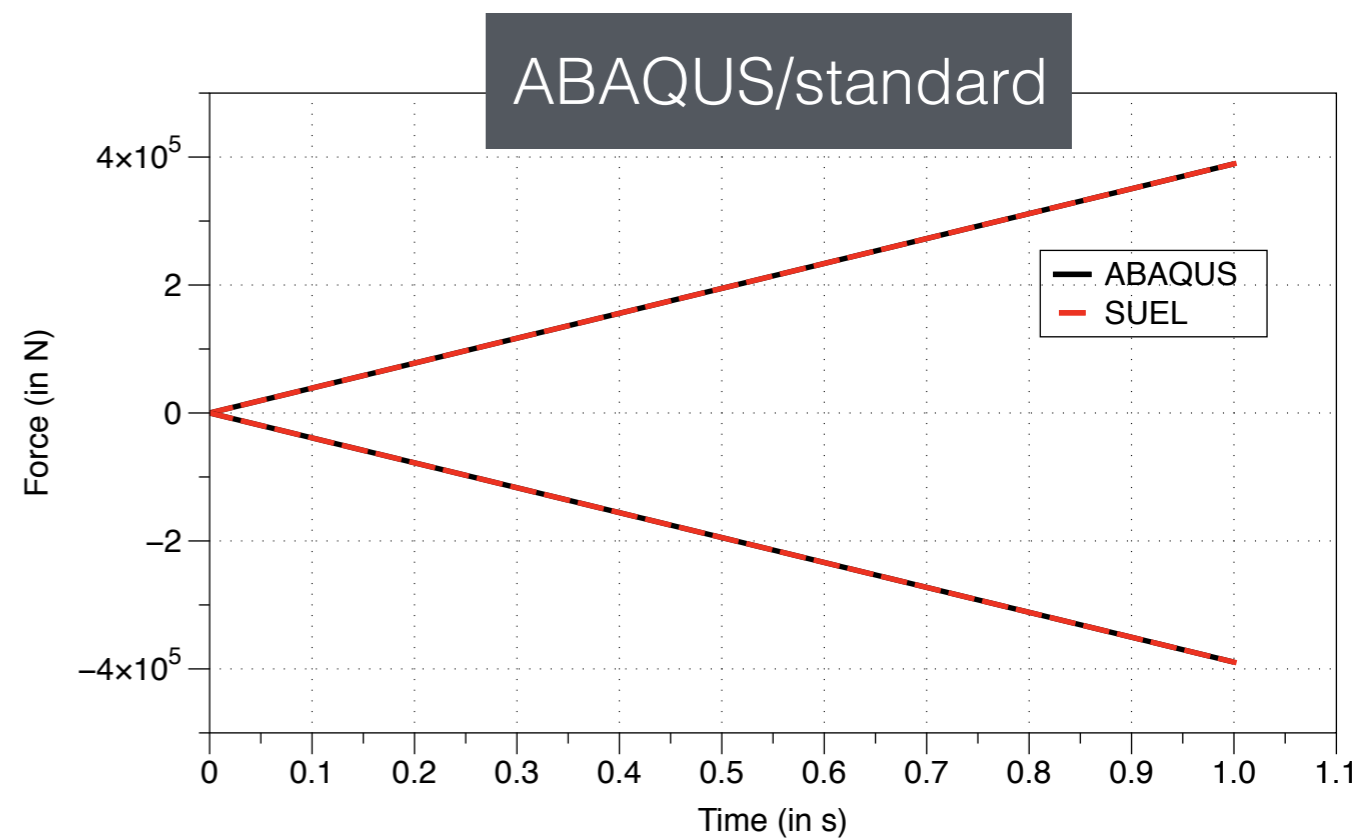
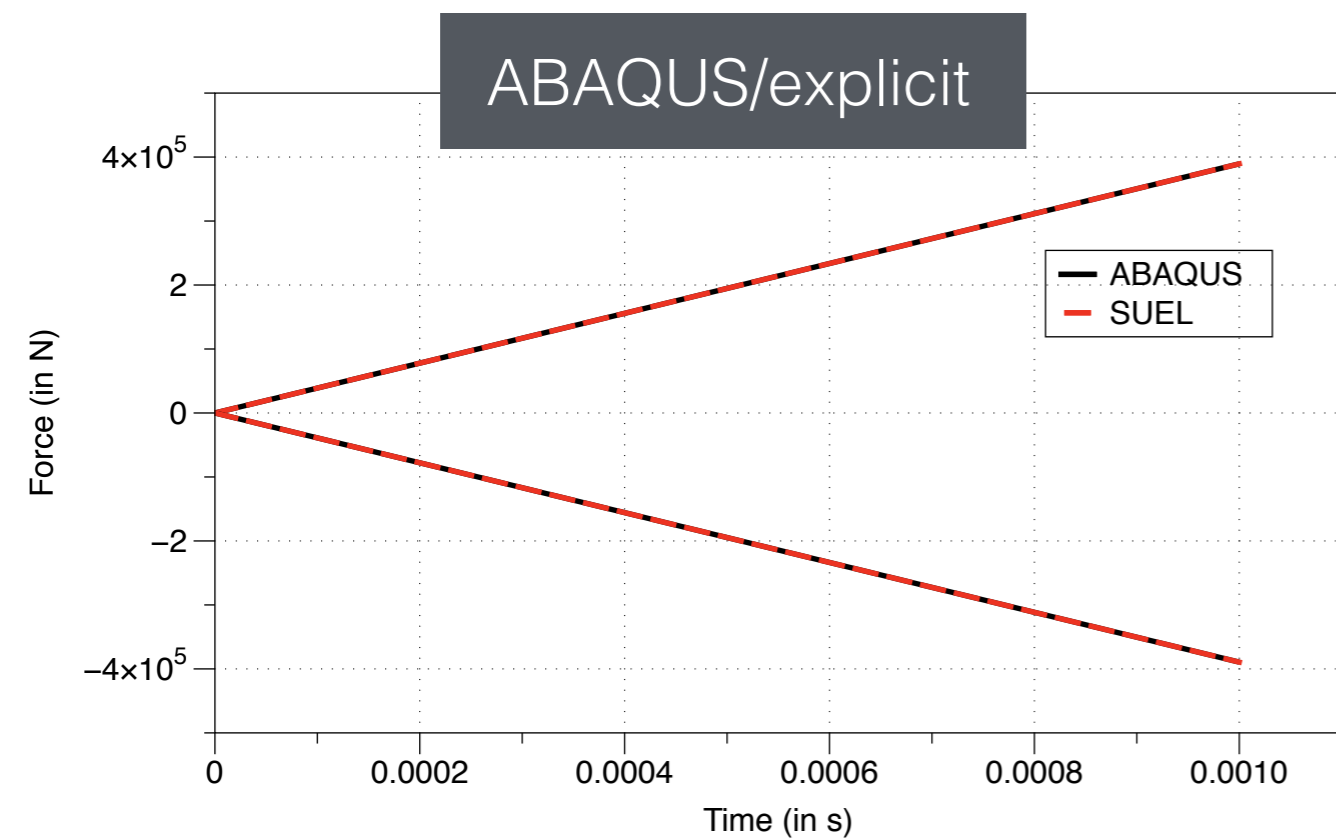
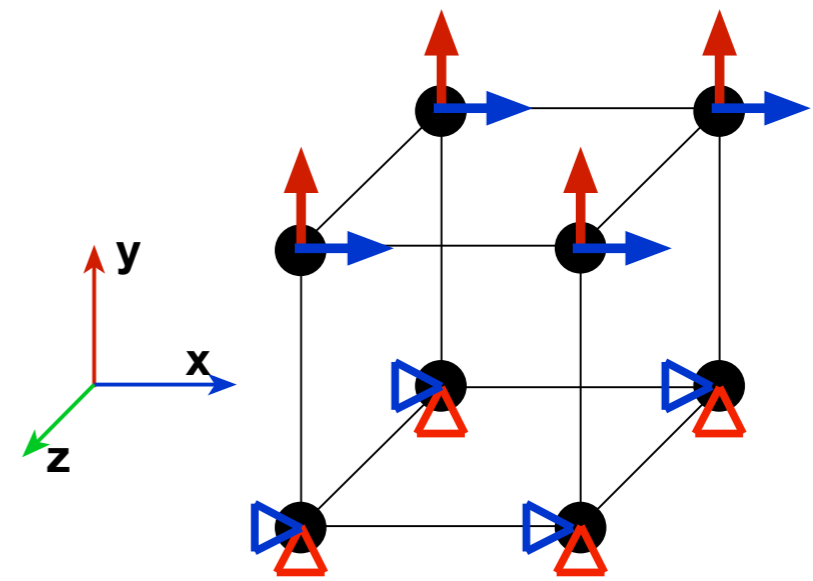
Compute Stable Time step
call compute_timestep(dtout,position,dm,
+                   nnode,ncoord,ncof,eltype)
```

Example, 3D solid element and 2D plane strain/
stress, small-strain/displacement formulation

$$\mathbf{u}(g, h) = N^N(g, h)\mathbf{u}^N \quad \text{Isoparametric element}$$

(V)UEL subroutine

- Verification with an ABAQUS element under mixed mode deformation with an elastic material.
- UEL+VUEL script => 2200 lines of code...



Conclusions

Why should we develop/implement something into ABAQUS?

- Lack of a particular model
- Improvement of an existing model

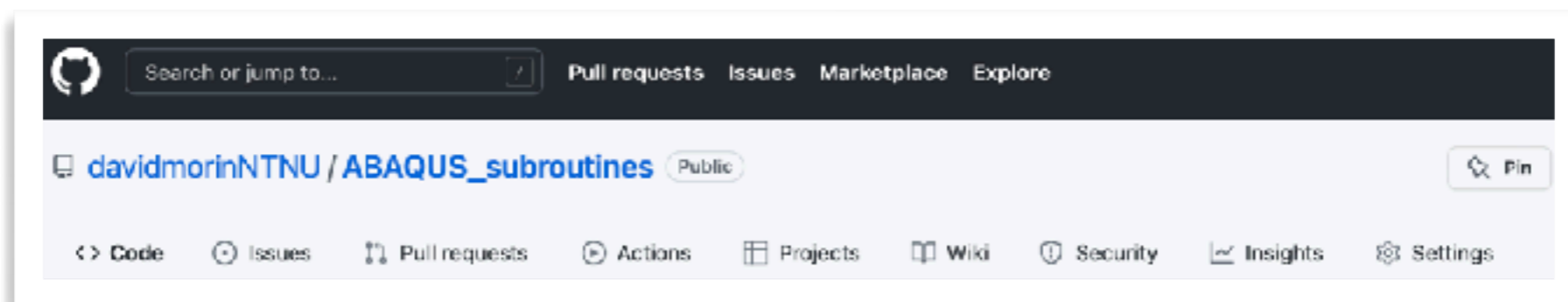
Things to consider before implementing any model:



- Can you work with an existing model?
- Will someone else use your code?

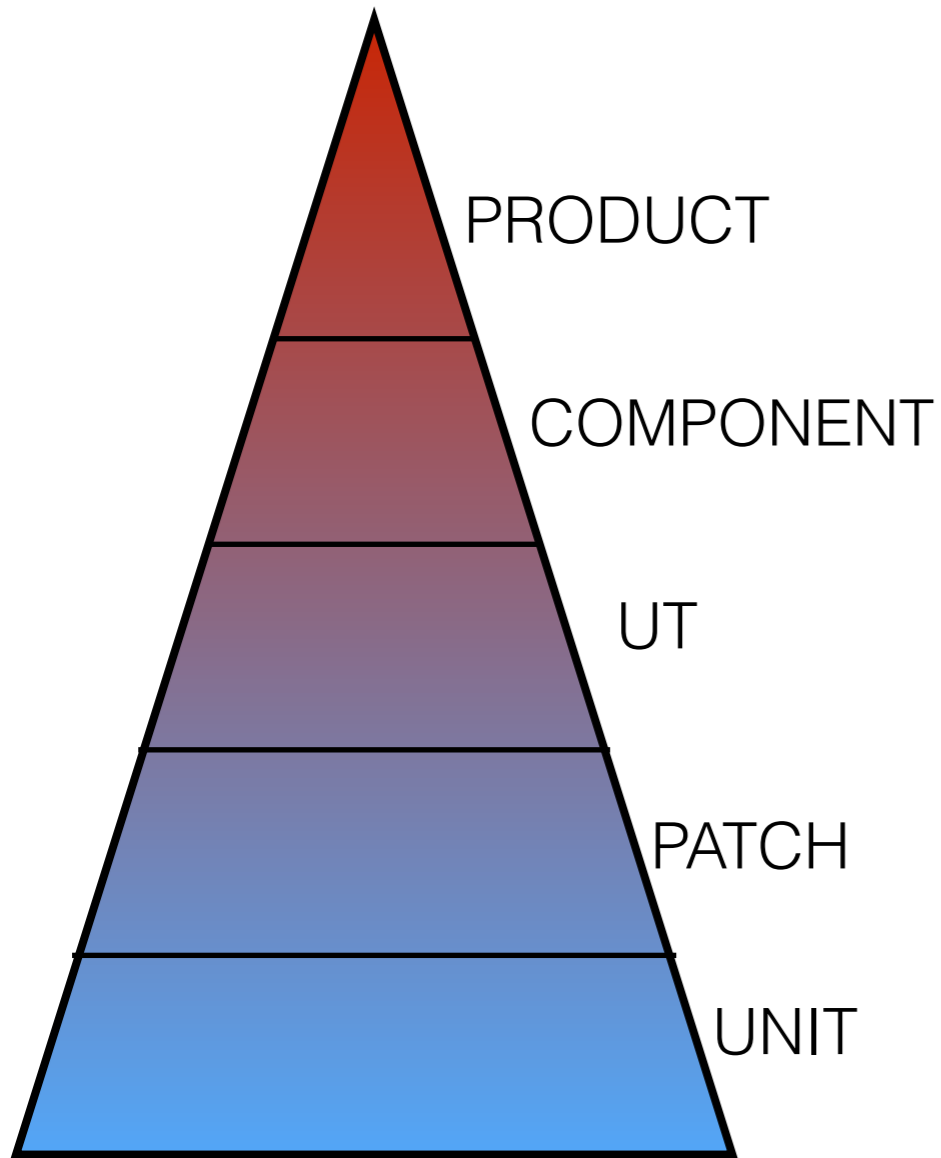
Use this as a starting point?

https://github.com/davidmorinNTNU/ABAQUS_subroutines

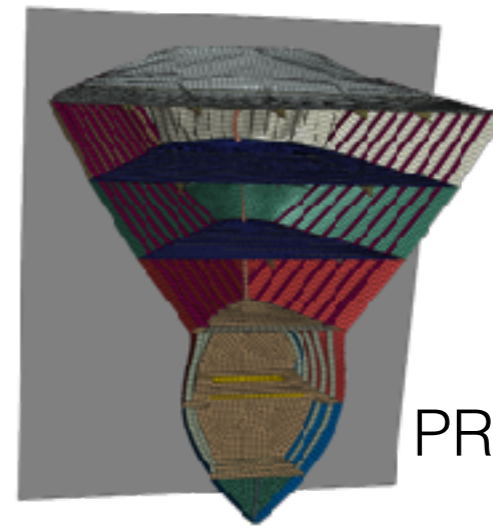
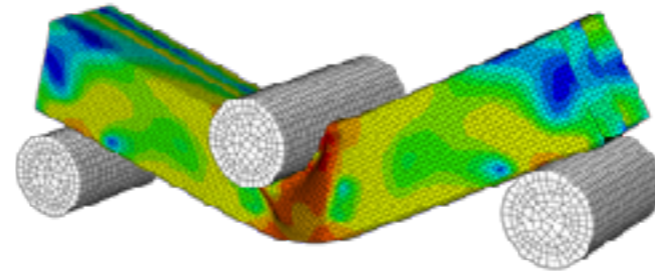


Conclusions

Verification of user-models:

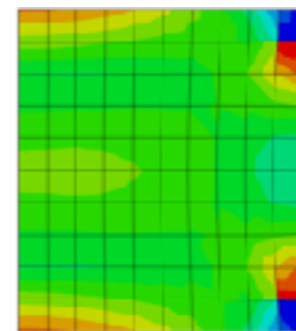
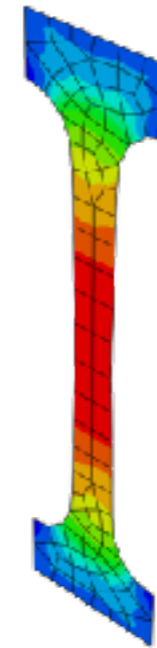


COMPONENT

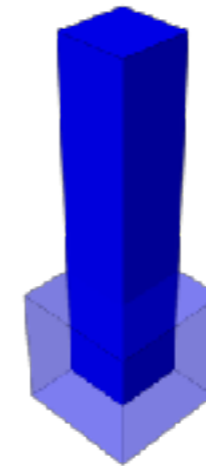


PRODUCT

UT



PATCH



UNIT

Thank you for your attention !